

# Complex Traffic Dynamics on Freeways

Prof. Dr. rer. nat. Dirk Helbing

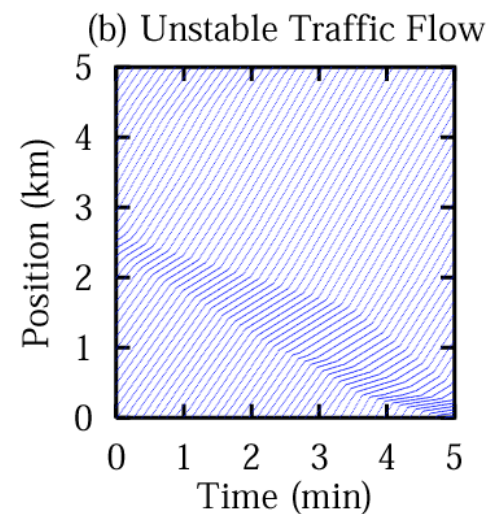
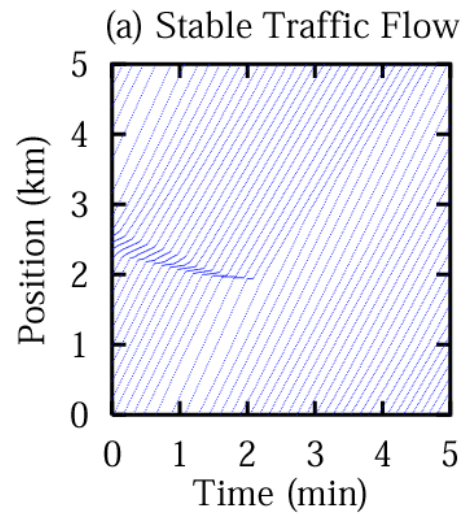
Chair of Sociology, in particular of Modeling and Simulation

[www.soms.ethz.ch](http://www.soms.ethz.ch)

with Anders Johansson, Martin Treiber, Arne Kesting,  
Stefan Lämmer, Martin Schönhof, and others

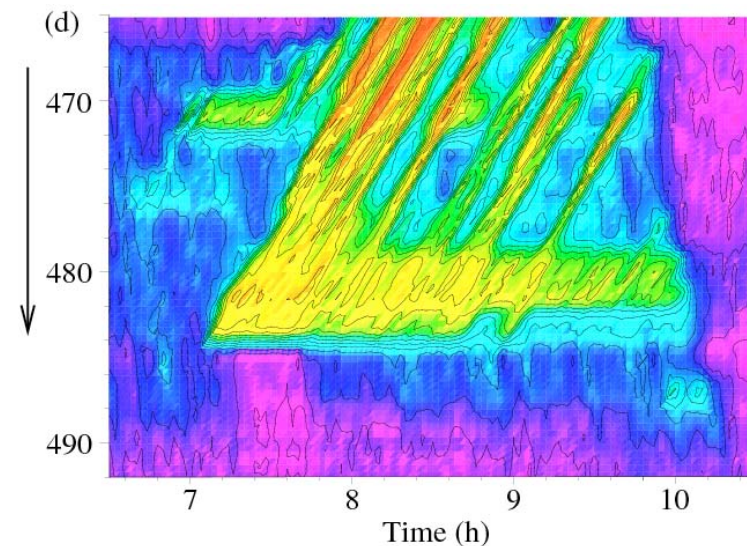
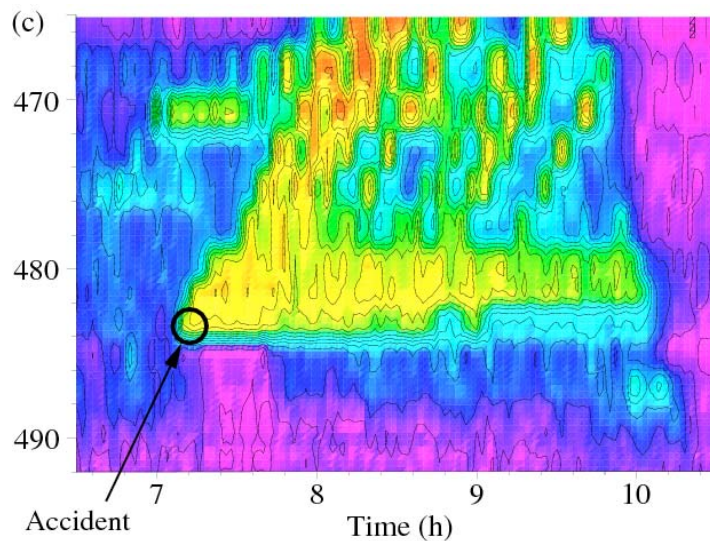
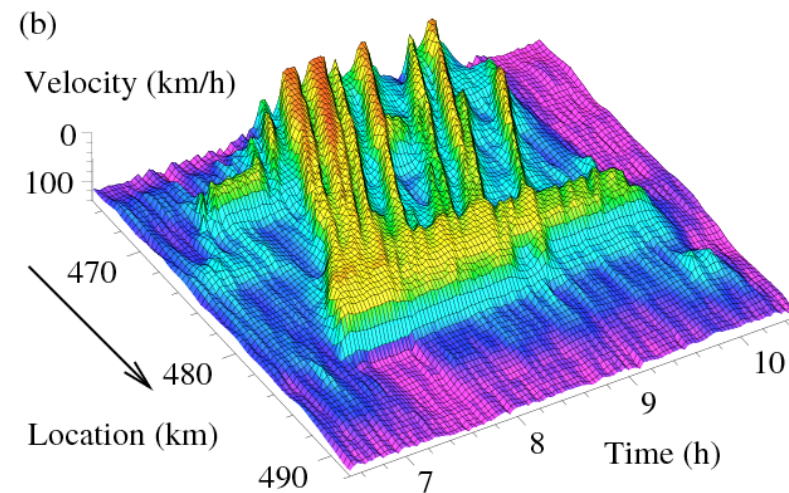
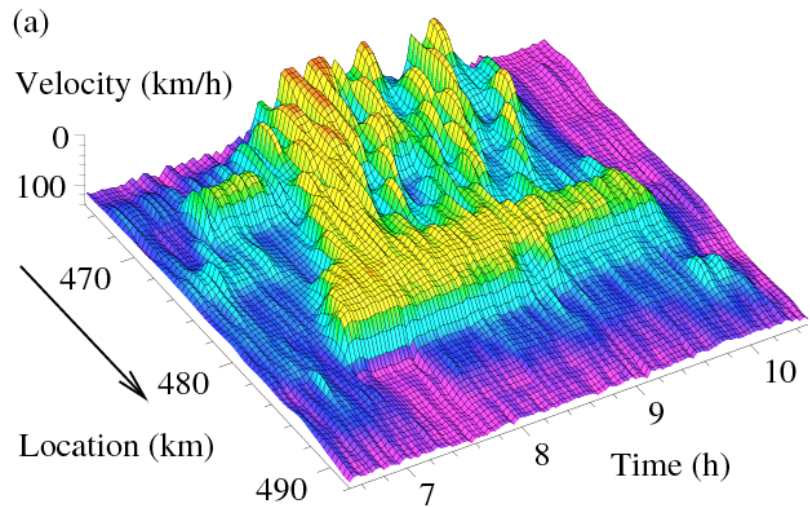


# Instability of Traffic Flow

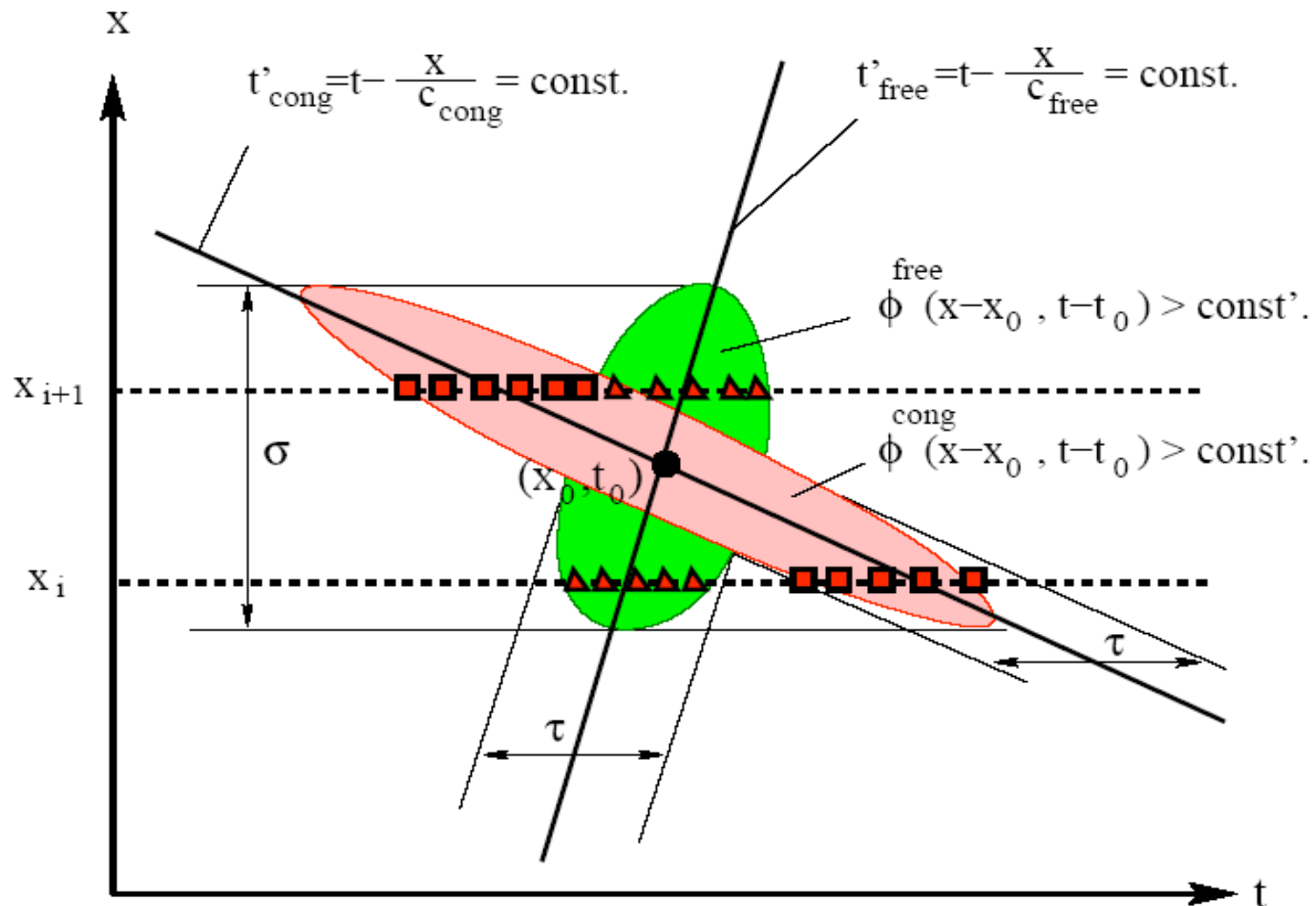


Source: Sugiyama et al.

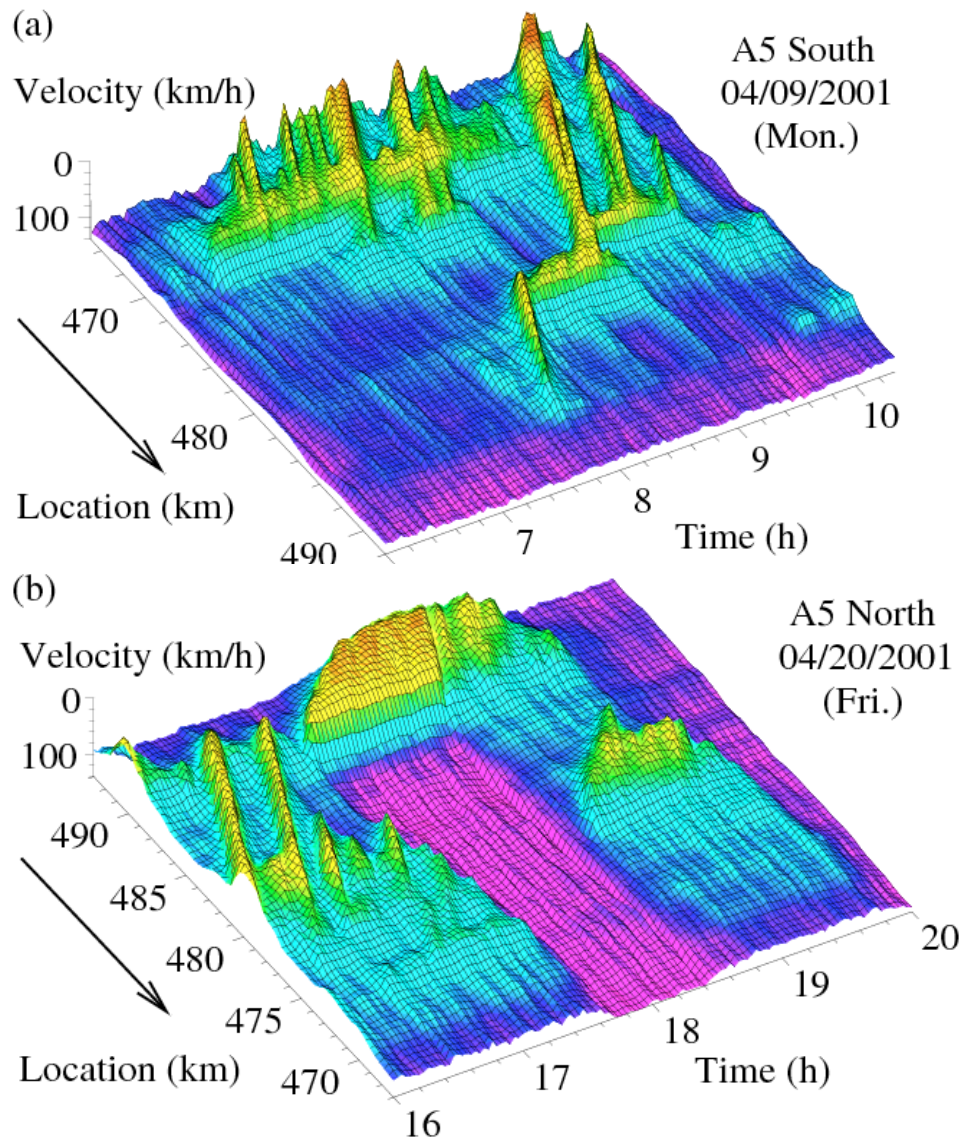
# How to Analyze the Cross-Sectional Traffic Data



# How the Adaptive Smoothing Method Works



## Complex Congestion Patterns

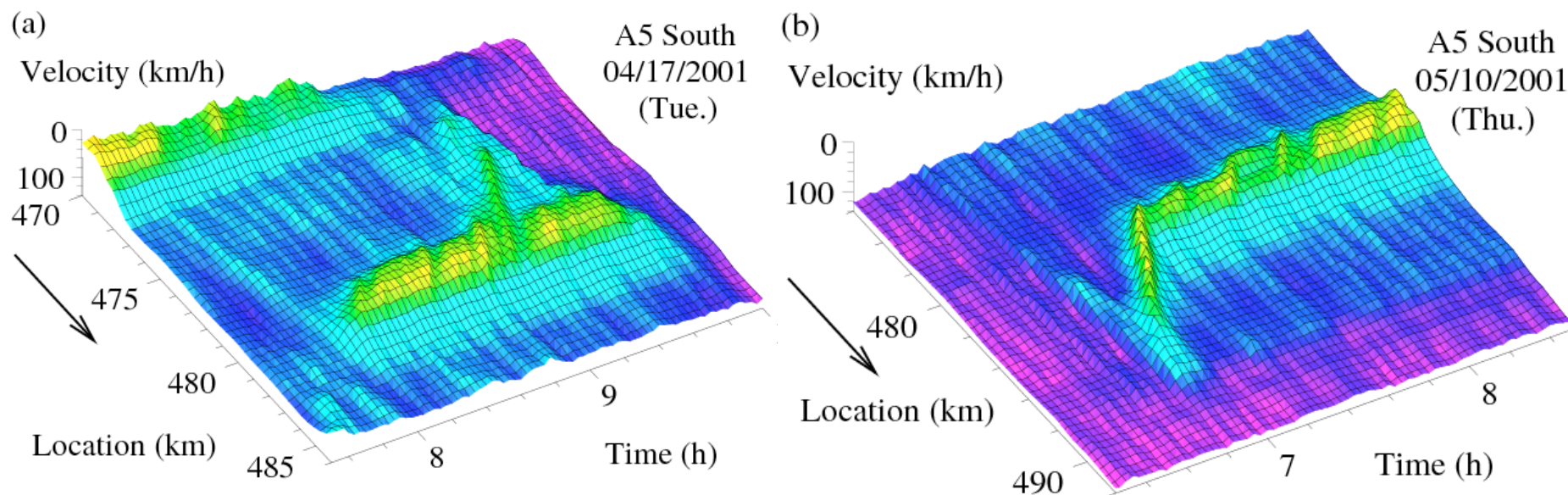


The boomerang effect triggers a pinned localized cluster, which grows up to the off-ramp. This generates a moving localized cluster, which causes an accident at kilometer 479.2. The off-ramp of Intersection Bad Homburg allows for stop-and-go waves.

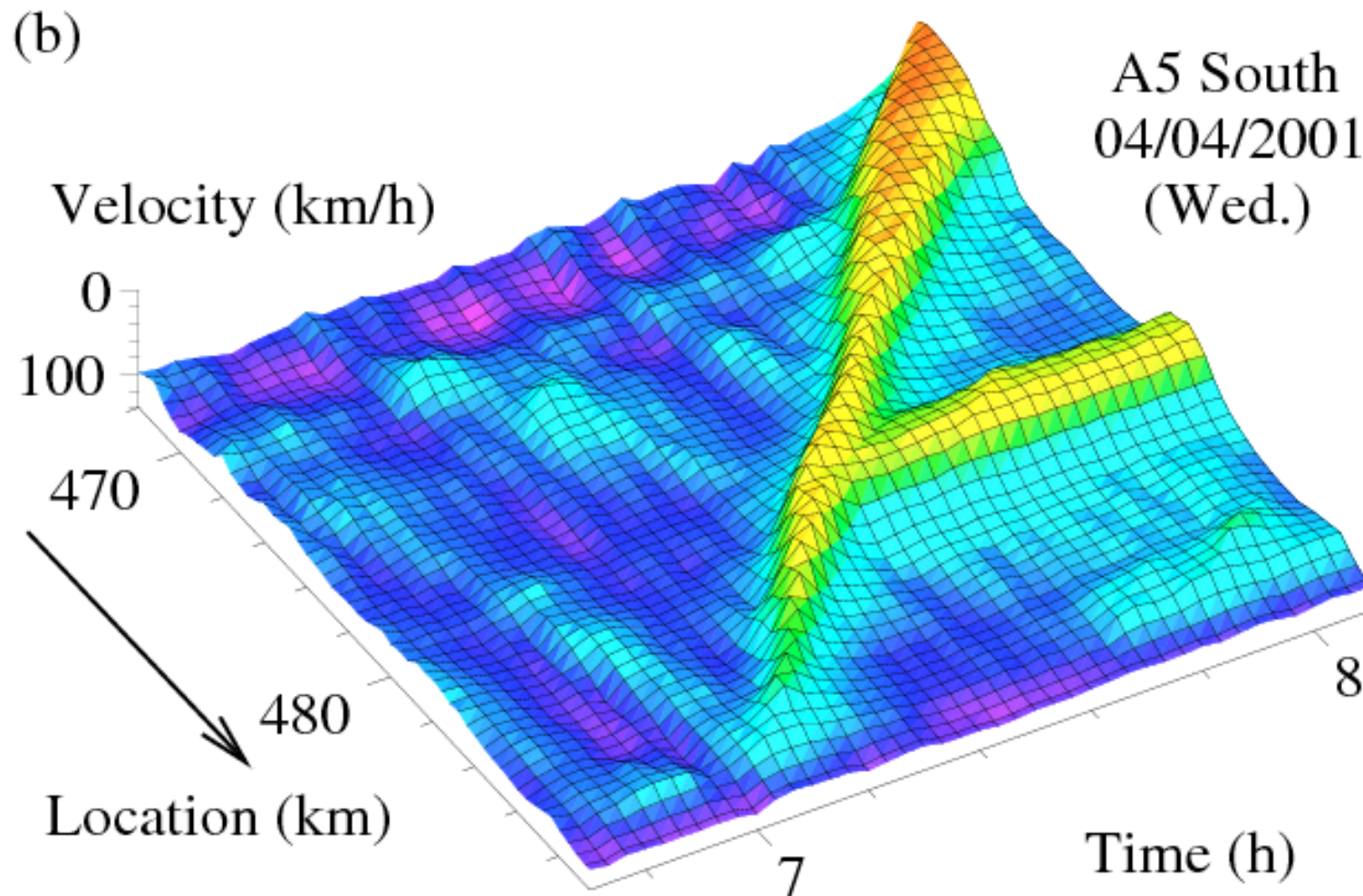
An accident at kilometer 487.5 causes homogeneous congested traffic. After the accident has been cleared, the downstream front moves upstream to Intersection Frankfurt North-West. The off-ramp there mitigates the congestion, resulting in oscillating congested traffic.

## Elementary Traffic Patterns: Examples of Pinned Localized Clusters

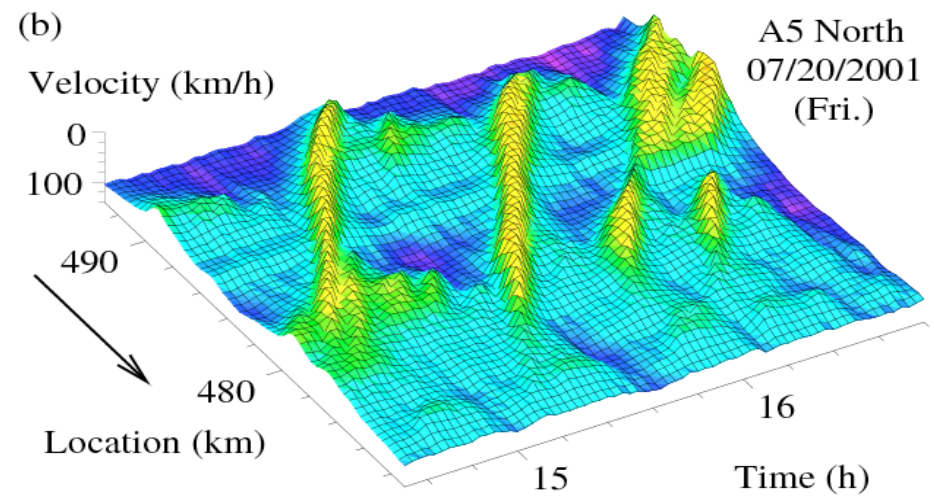
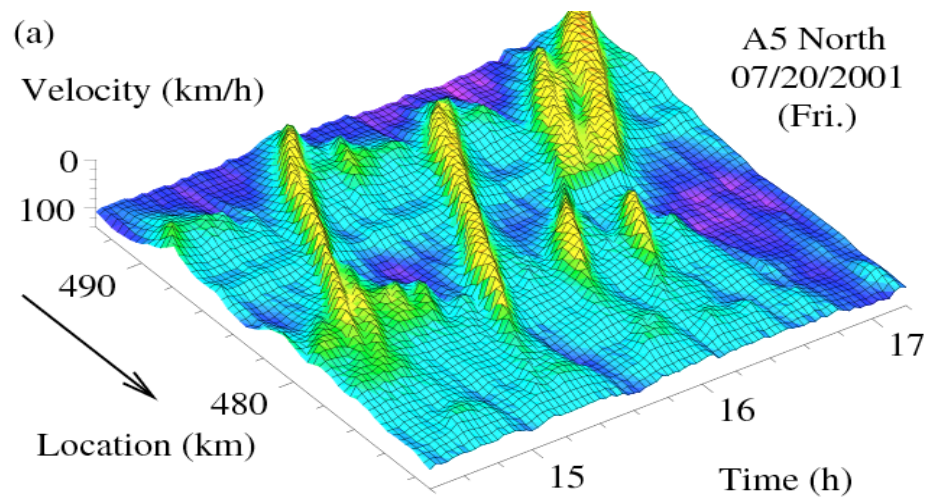
The congested area remains localized as long as it does not reach the upstream end of the off-ramp.



## Elementary Traffic Patterns: Example of a Moving Localized Cluster

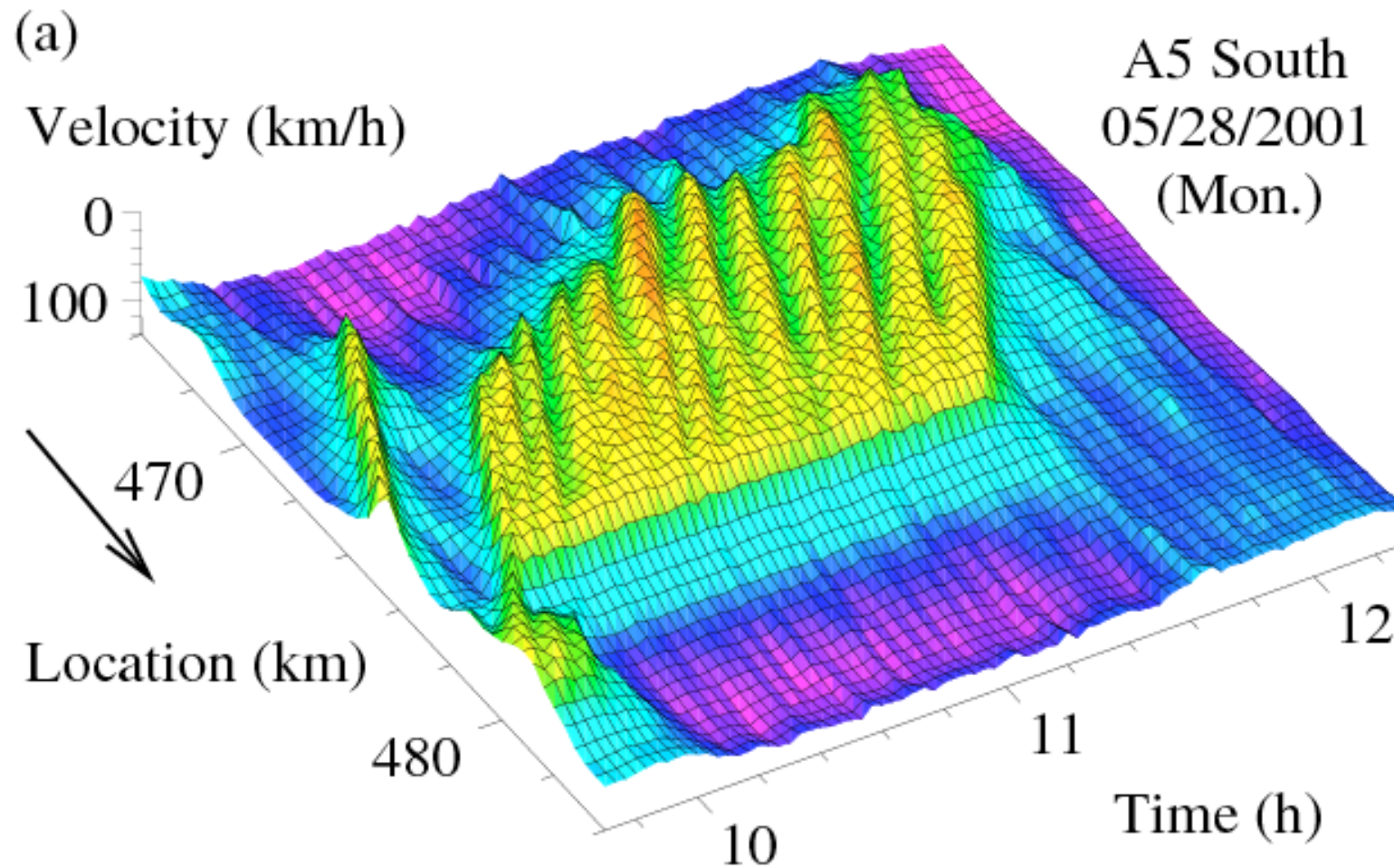


# Elementary Traffic Patterns: Examples of Stop-and-Go Waves

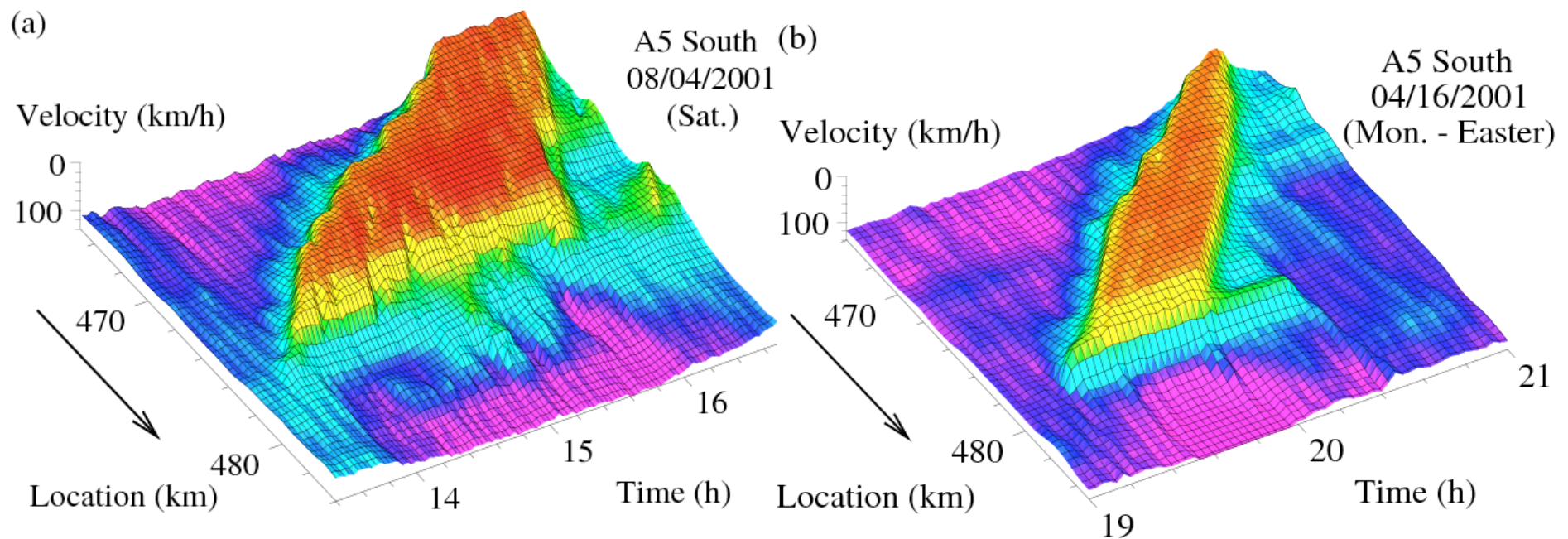




## Elementary Traffic Patterns: Oscillating Congested Traffic

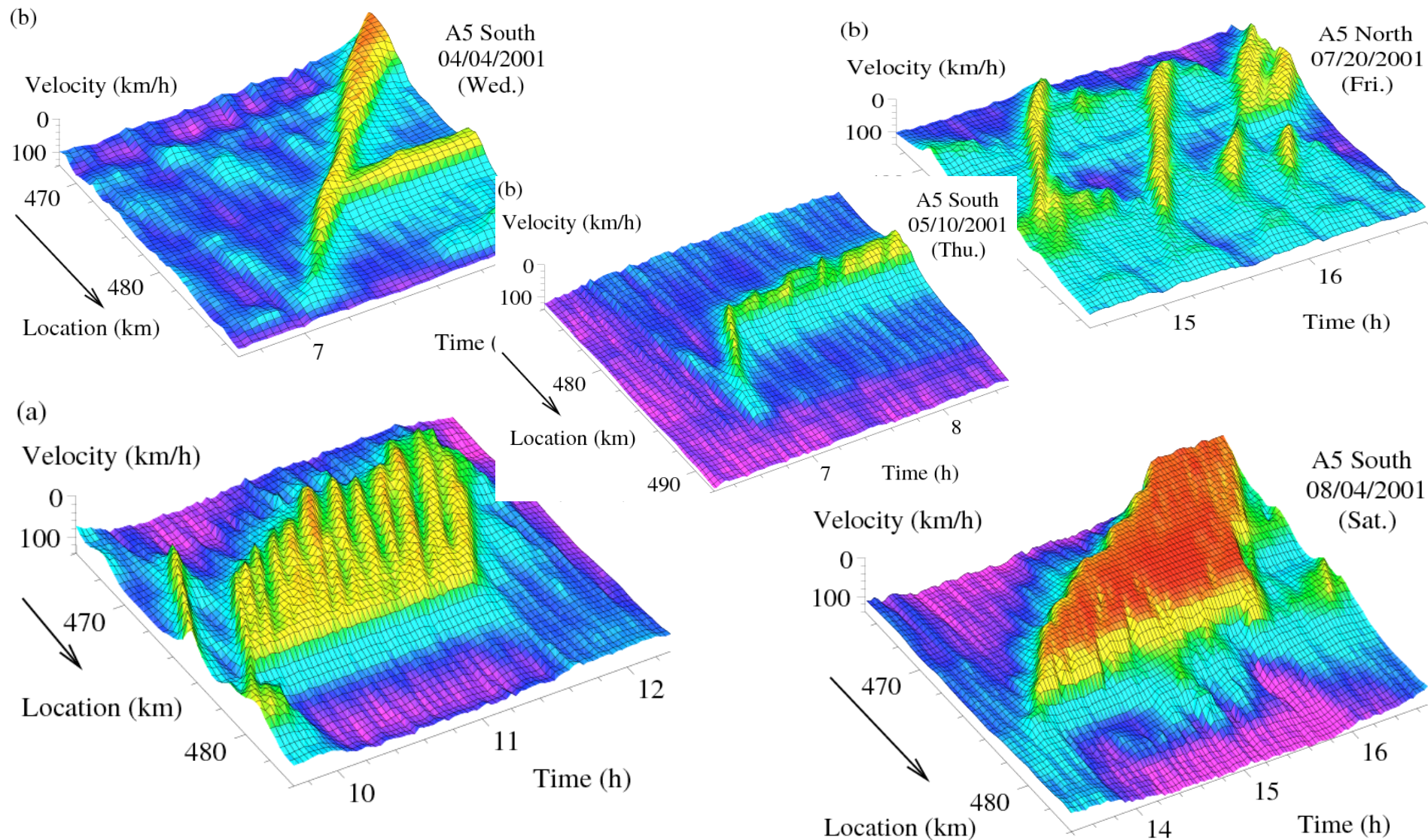


## Elementary Traffic Patterns: Homogeneous Congested Traffic



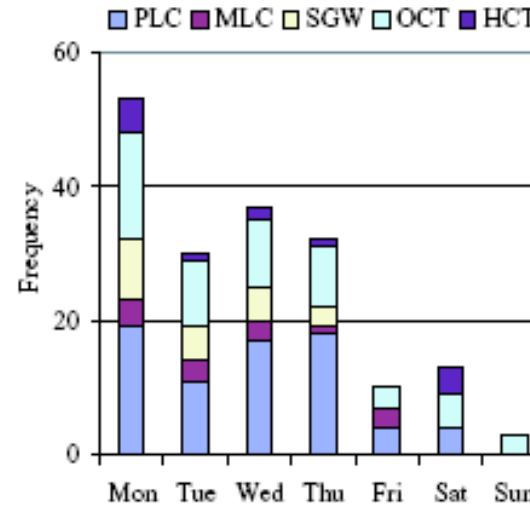
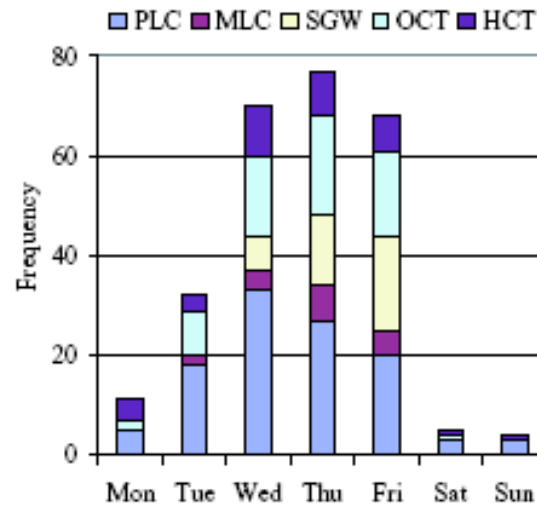
Homogeneous congested traffic **requires large bottleneck strengths** exceeding about 700 vehicles per kilometer and lane, which usually occur after serious accidents only. That is, if cases of accidents are excluded from the data set, one cannot find homogeneous congested traffic (if street capacities are properly dimensioned).

# Summary of Elementary Congestion Patterns

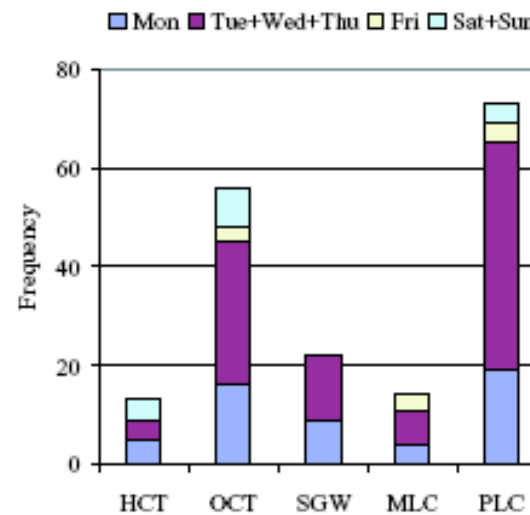
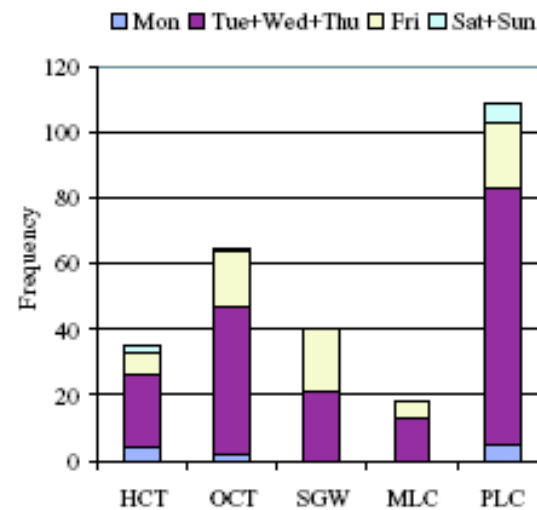


# Traffic States Depend on the Weekday

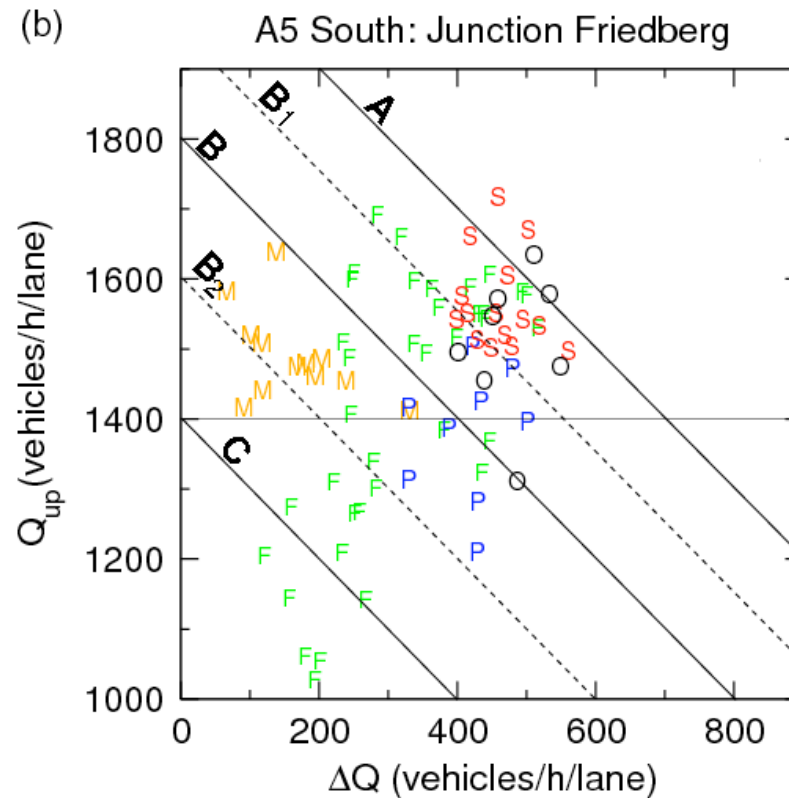
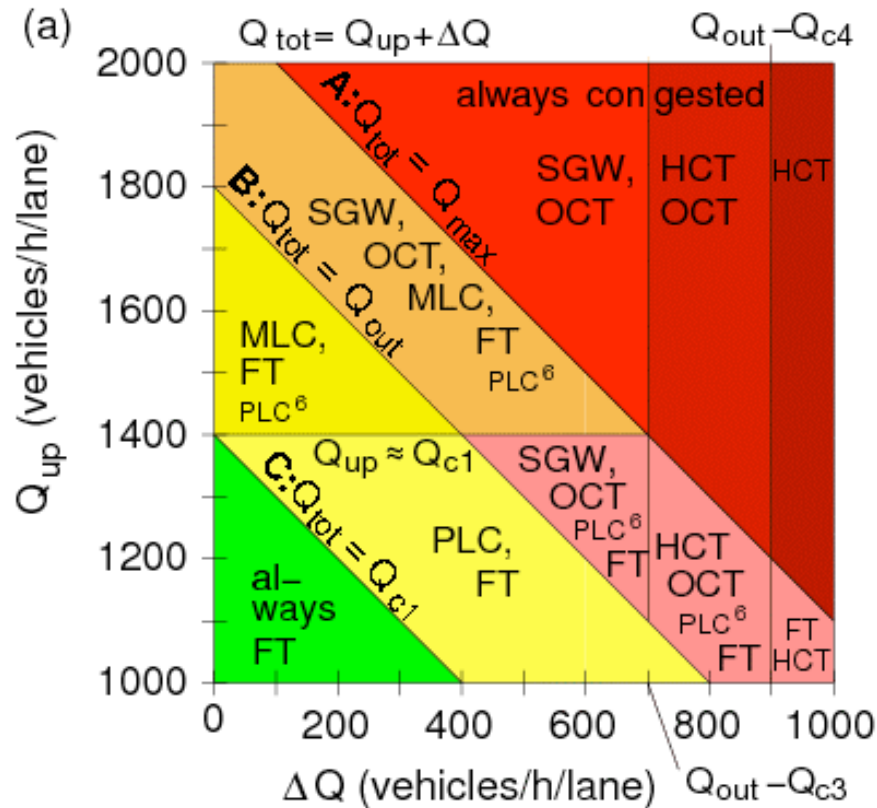
Direction  
North of  
Frankfurt



Direction  
towards  
Frankfurt

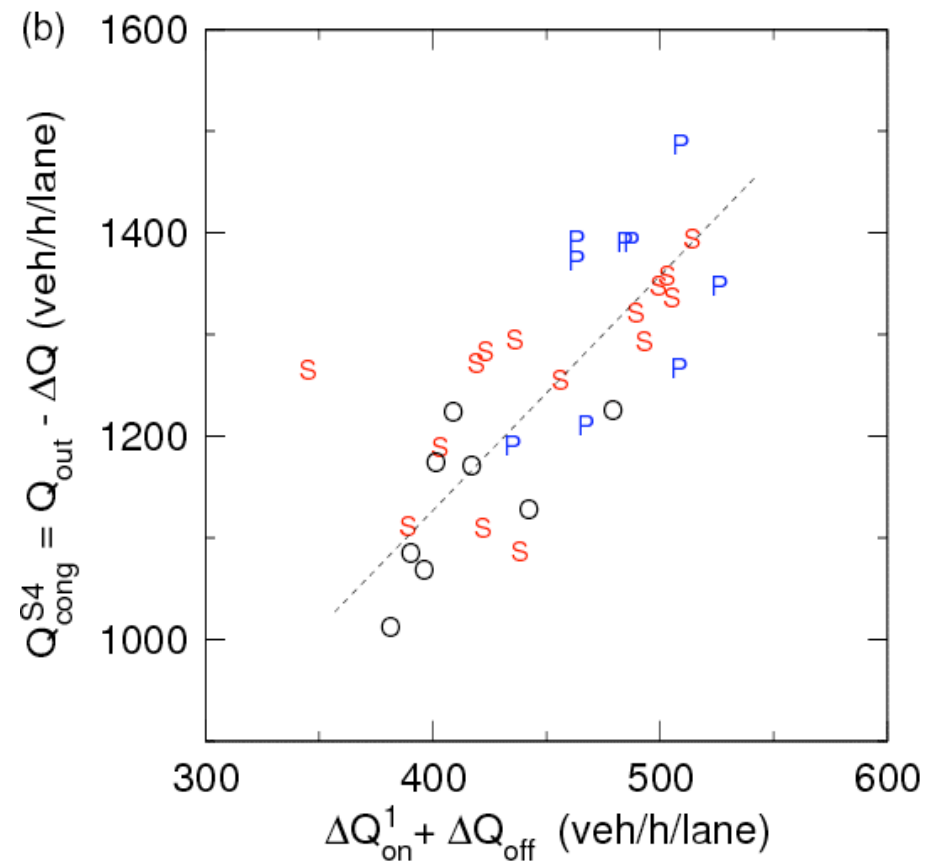
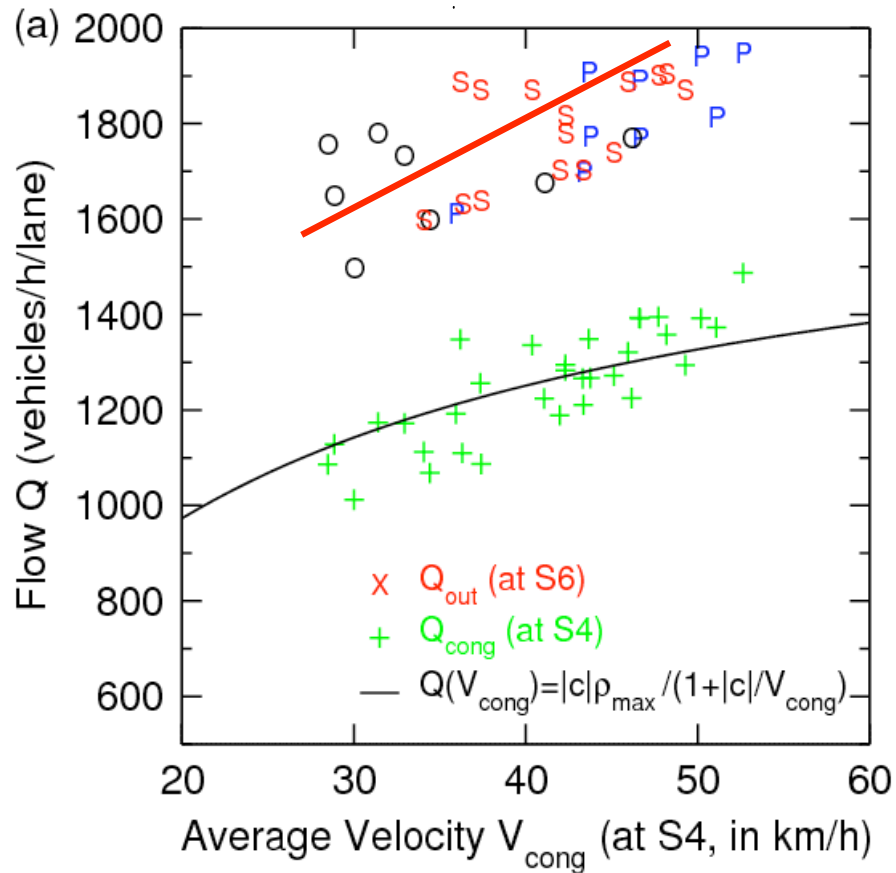


# Theoretical vs. Empirical Phase Diagram



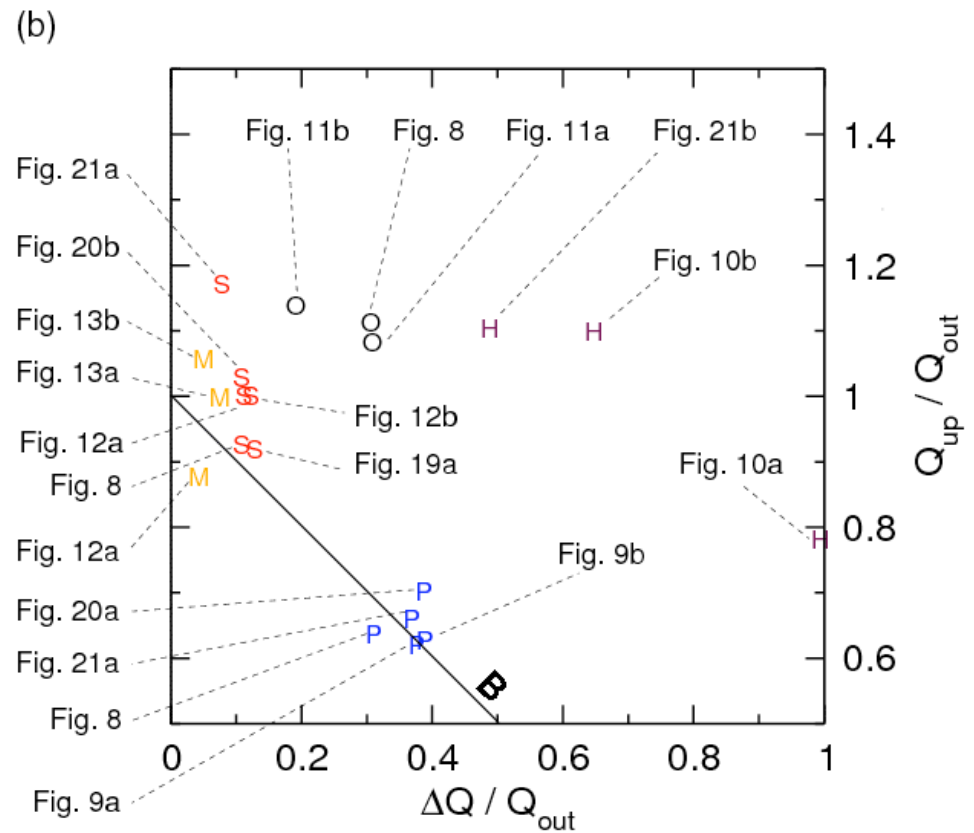
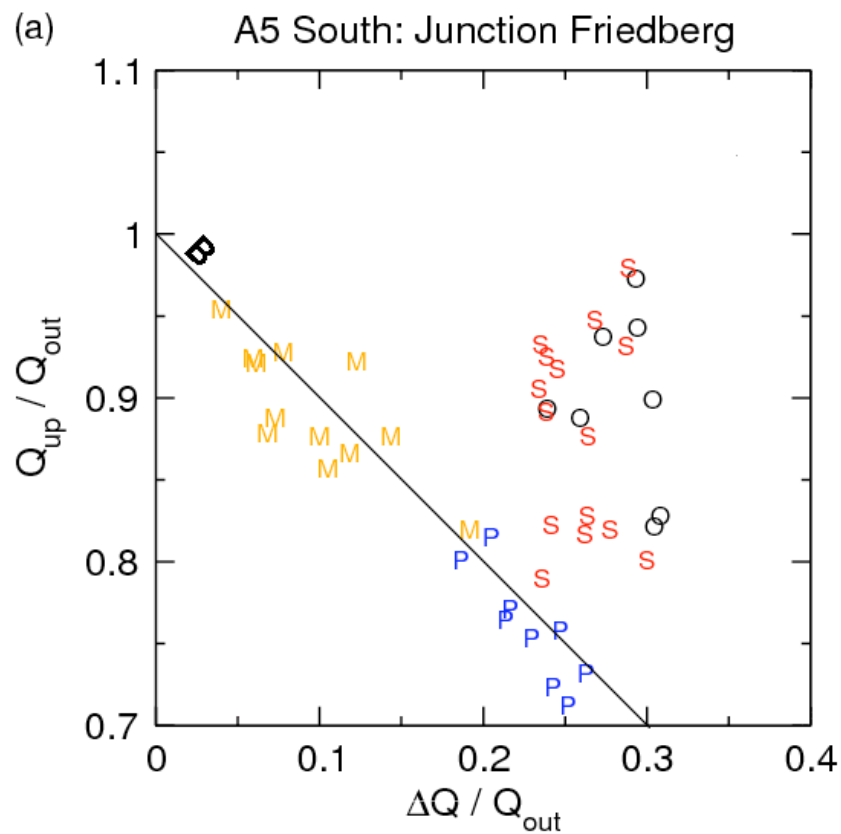
The outflow varies between B1 and B2. For statistical reasons?

# The Outflow Correlates with Other Traffic Variables

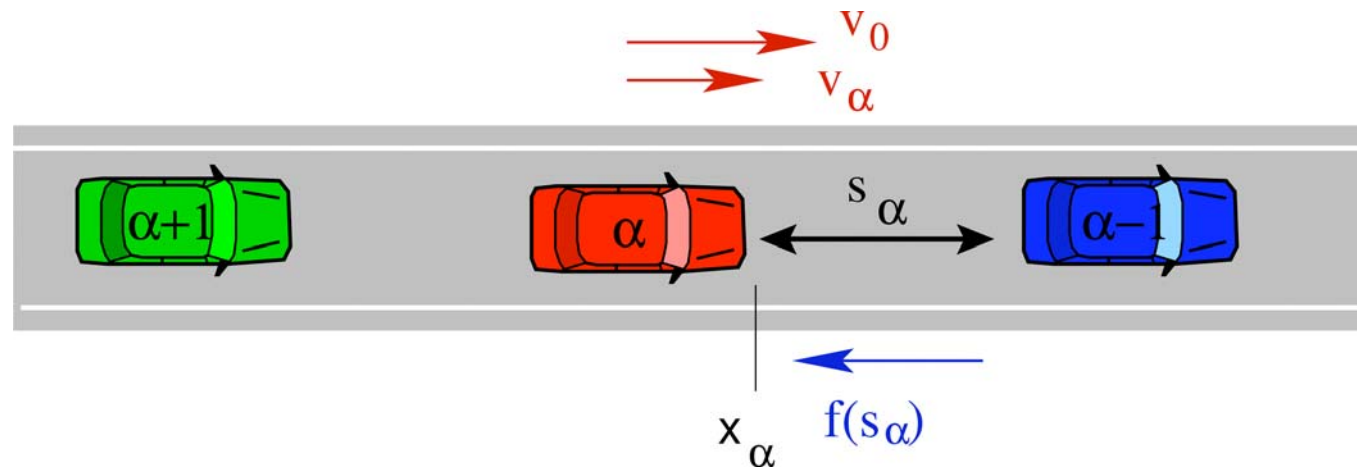


# Empirical Phase Diagram for Scaled Flows

A scaling by the outflow, that varies from day to day, gives a clearer picture.



# The Intelligent-Driver Model (IDM)



- Equations of motion:

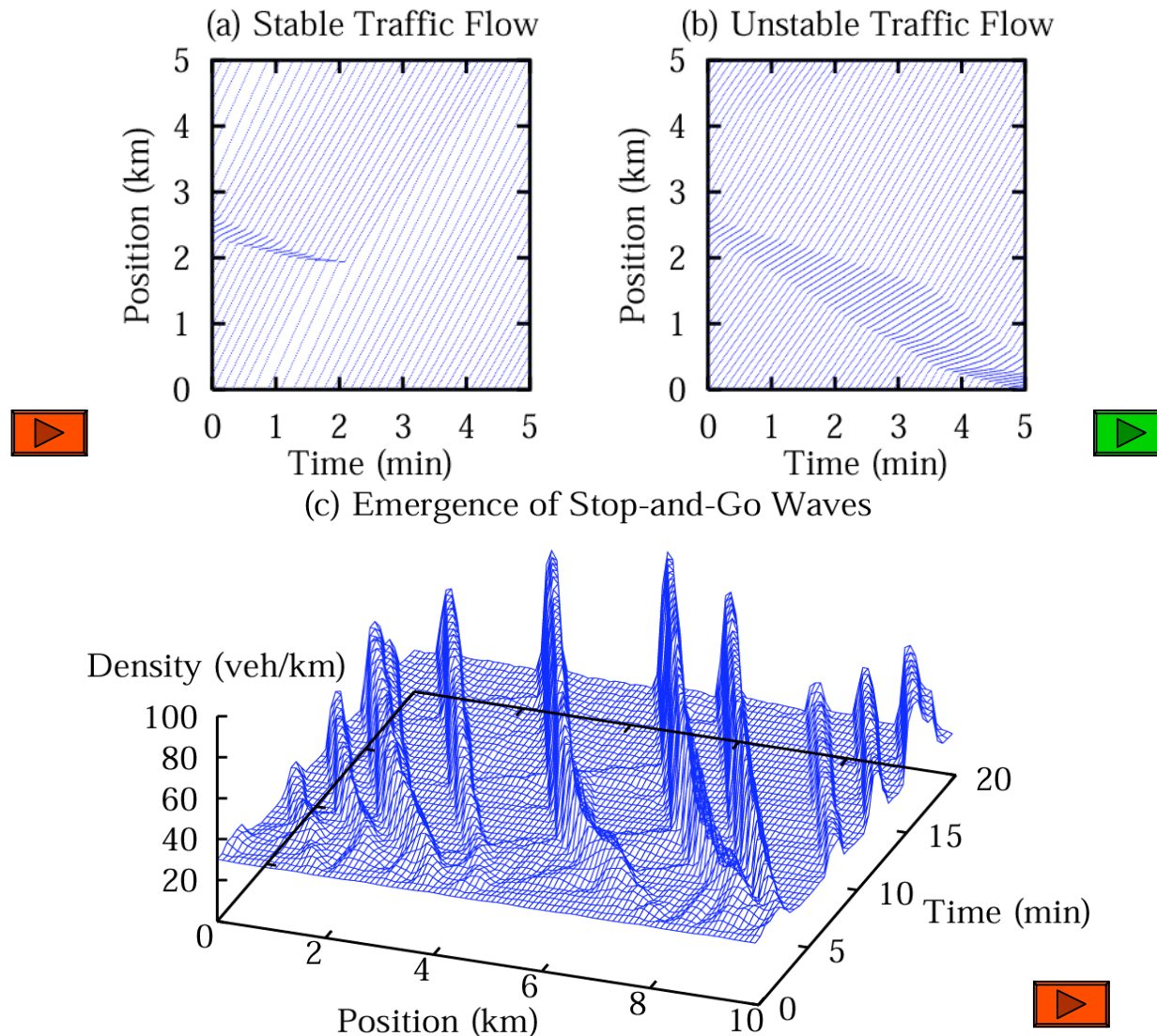
$$\begin{aligned} \dot{x}_\alpha &= v_\alpha, \\ \dot{v}_\alpha &= a \left[ \underbrace{1 - \left(\frac{v_\alpha}{v_0}\right)^\delta}_{\text{Beschleunigung}} - \underbrace{\left(\frac{s^*(v_\alpha, \Delta v_\alpha)}{s_\alpha}\right)^2}_{\text{Bremsverzögerung}} \right] \end{aligned}$$

- Dynamic desired distance

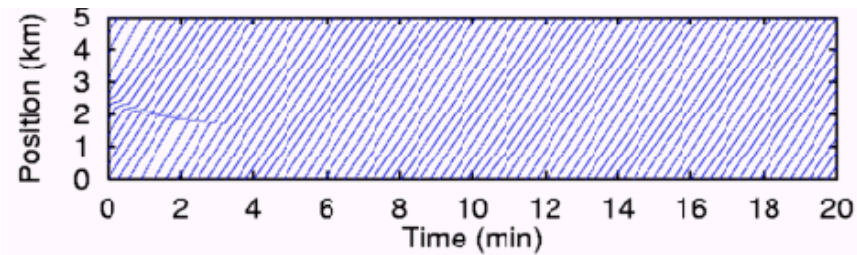
$$s^*(v, \Delta v) = \underbrace{s_0}_{\text{Mindestabstand}} + \underbrace{vT}_{\text{“Sicherheits”-abstand}} + \underbrace{\frac{v\Delta v}{2\sqrt{ab}}}_{\text{dynamischer Teil}}$$



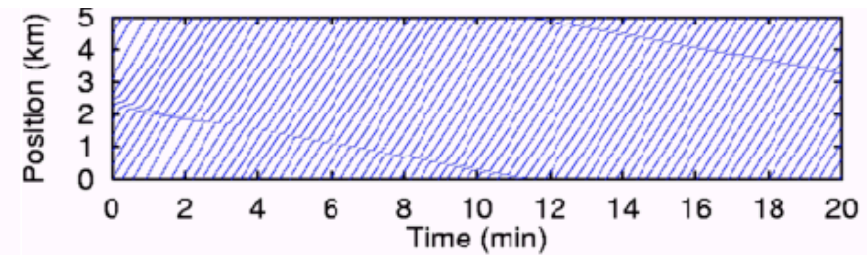
# Instability of Traffic Flow



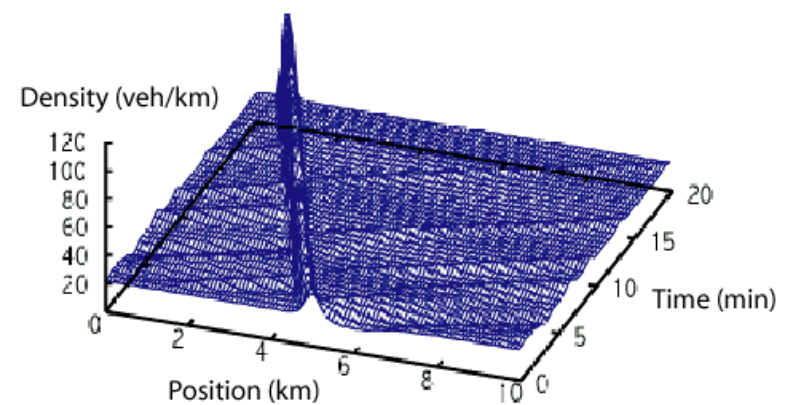
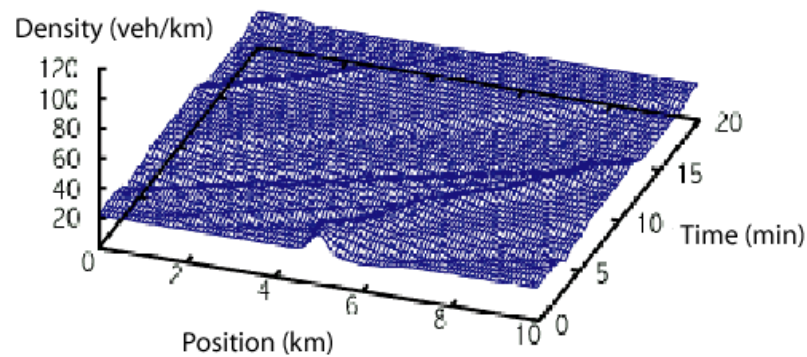
# Metastability of Traffic Flow



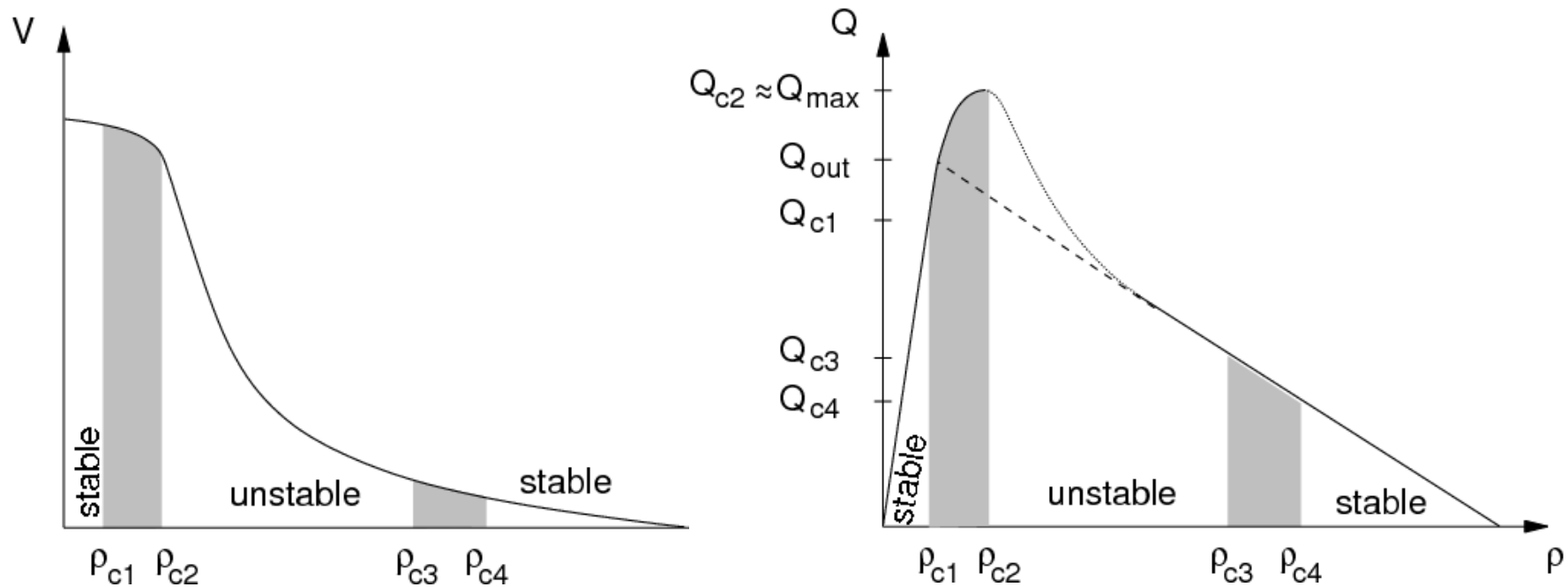
Decay of a Subcritical Perturbation



Growth of a Supercritical Perturbation



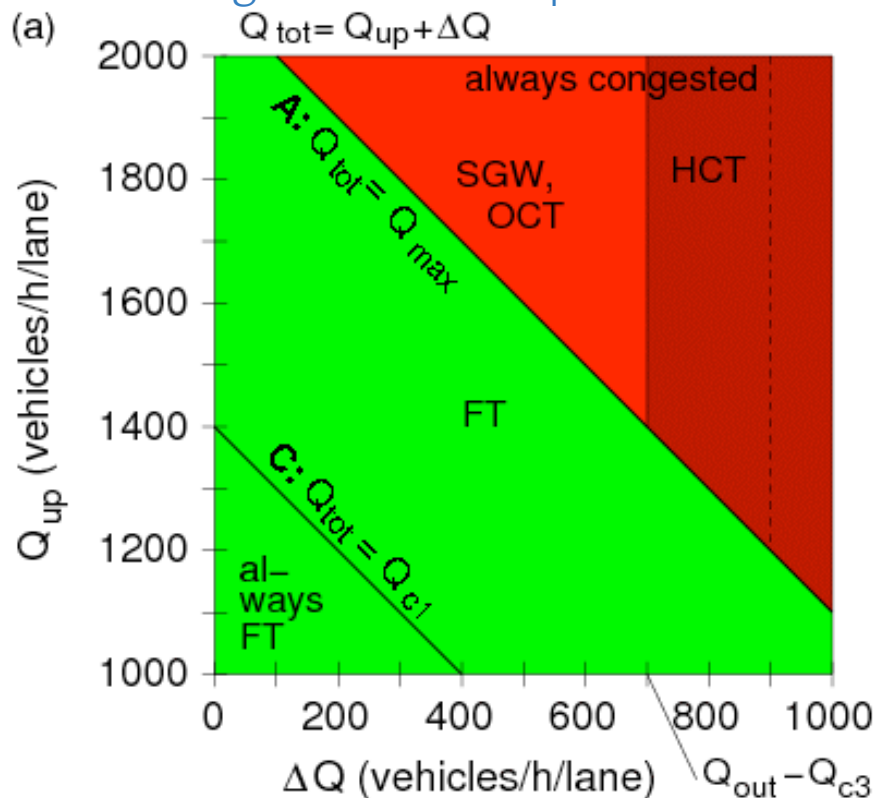
## Assumed Instability Diagram



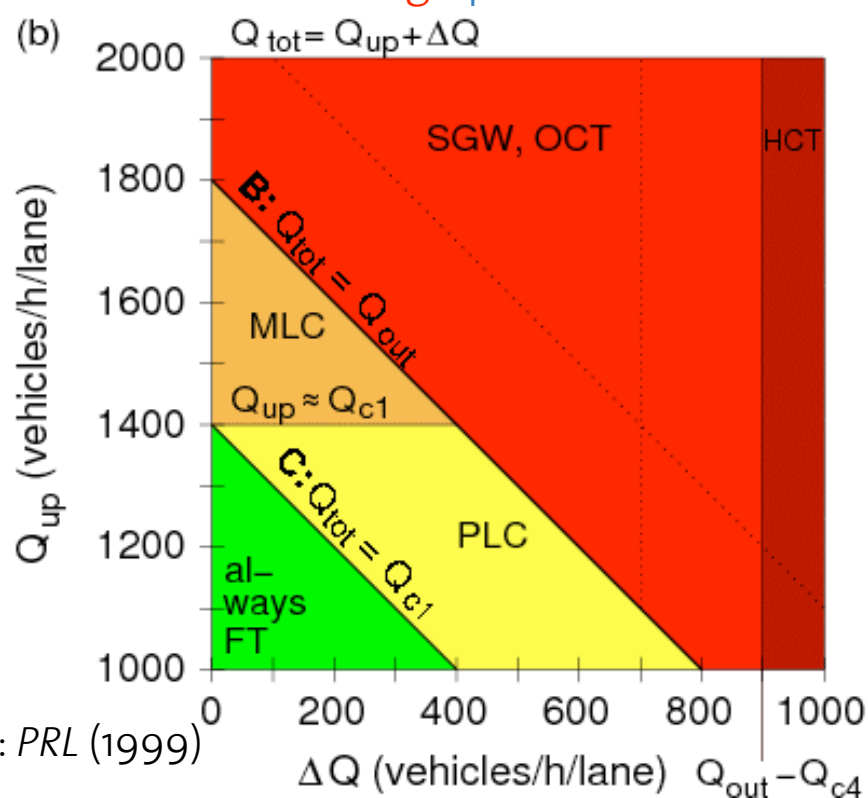
Grey areas = metastable regimes, where result depends on perturbation amplitude

# Phase Diagram of Traffic States and Universality Classes

Phase diagram for **small** perturbations



for **large** perturbations

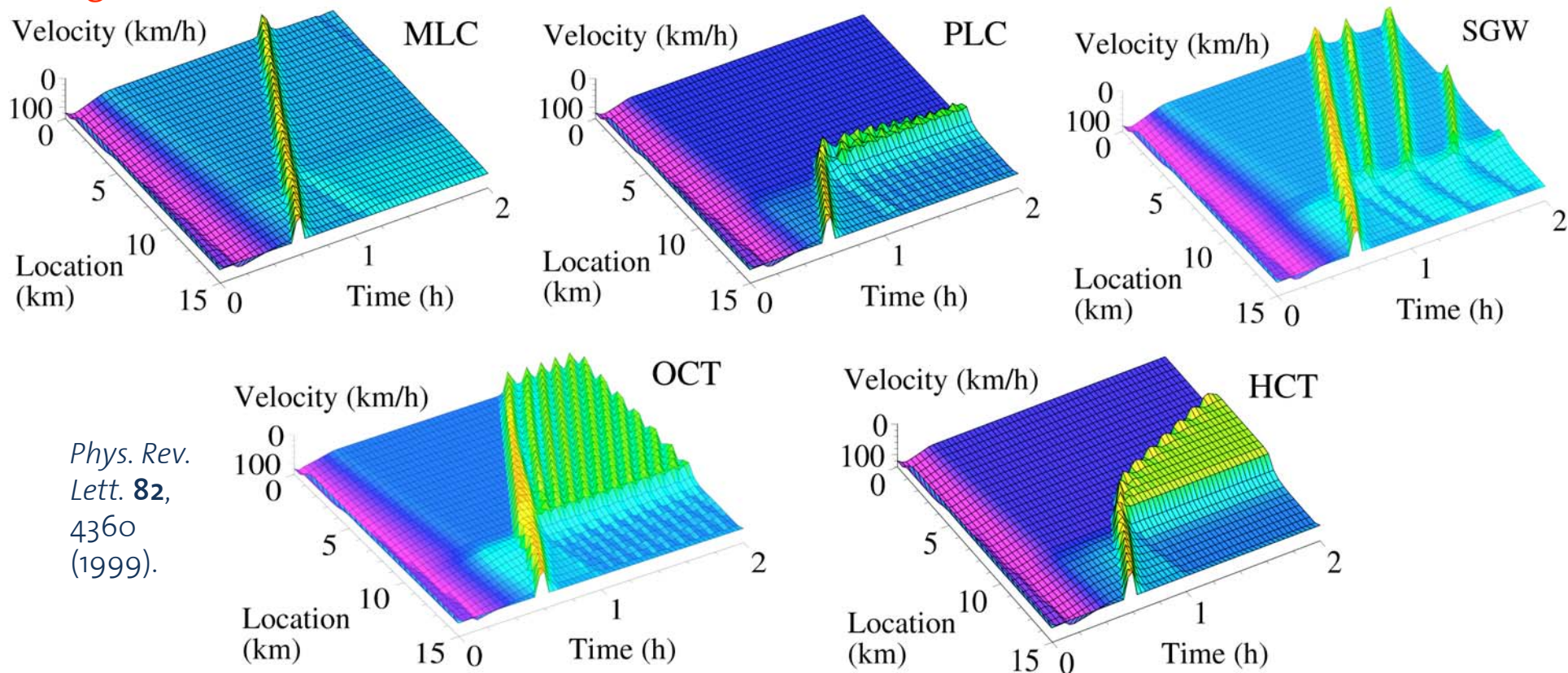


After: PRL (1999)

Phase diagrams are not only important to **understand the conditions** under which certain traffic states emerge. They also allow one to **categorize** the more than 100 traffic models into different **universality classes**. From the universality class that reproduces the empirically observed stylized facts, one may choose any representative, e.g. the **simplest** or the **most accurate** one, **depending on the purpose**.

# Congested Traffic States Simulated with a Macroscopic Traffic Model

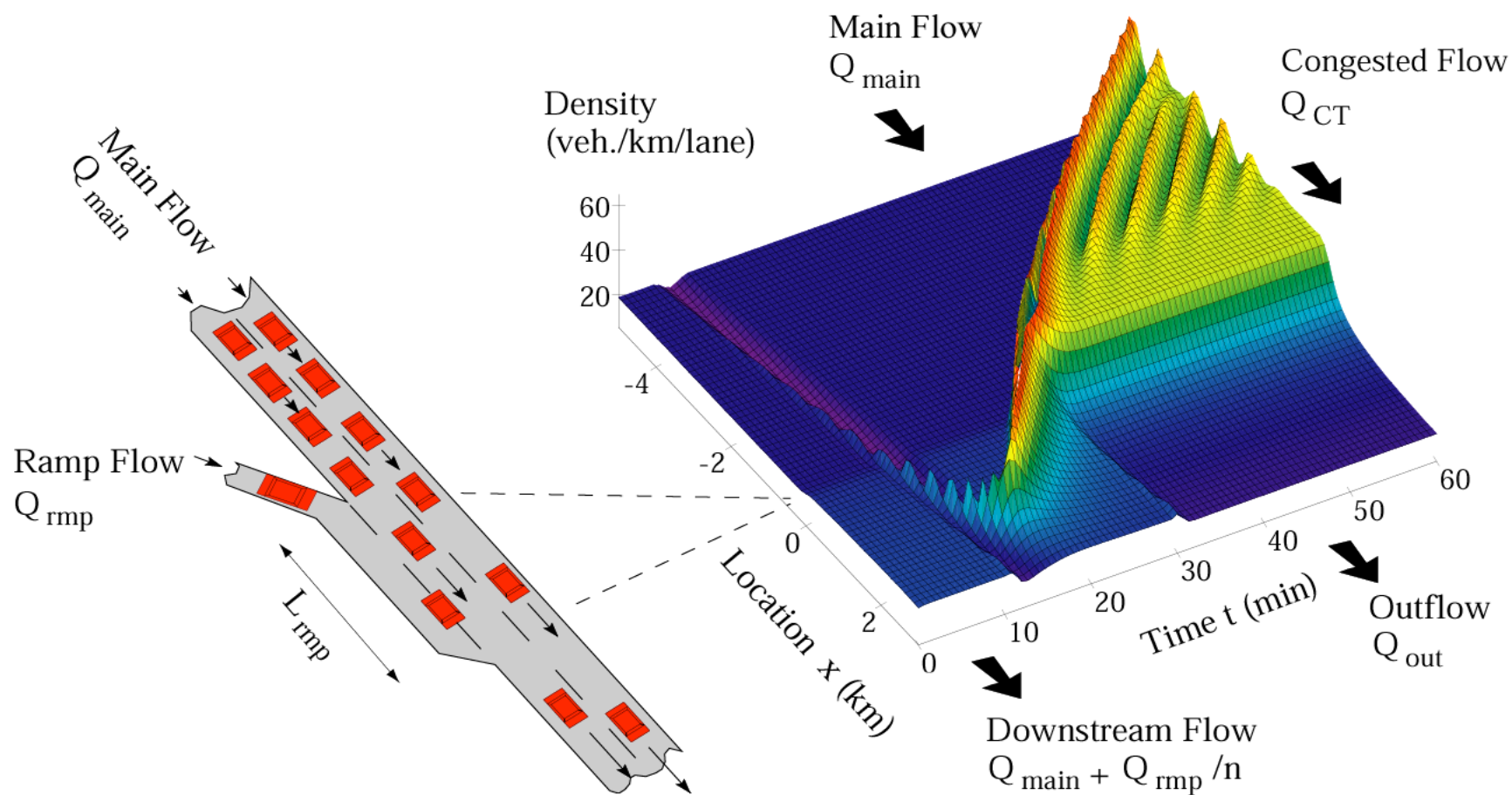
Perturbing traffic flows and, paradoxically, even *decreasing* them may sometimes cause congestion.



Similar congested traffic states are found for several other traffic models, including “microscopic” car-following models.

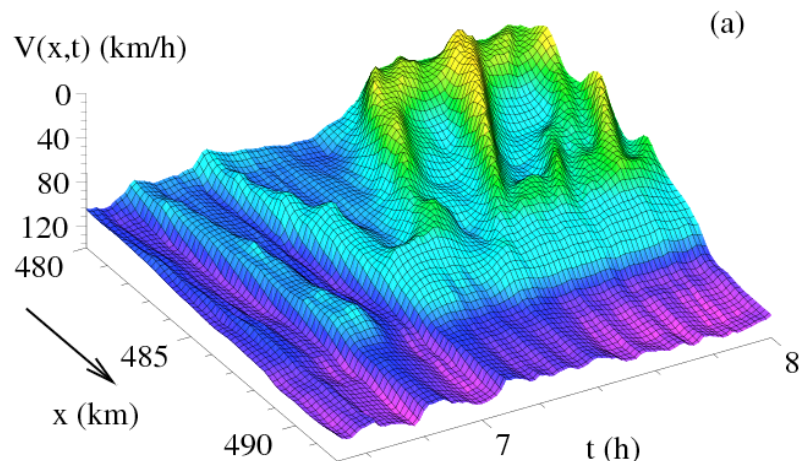
# Breakdown of Traffic due to a Supercritical Reduction of Traffic Flow

## Negative Perturbation Triggering Oscillating Congested Traffic

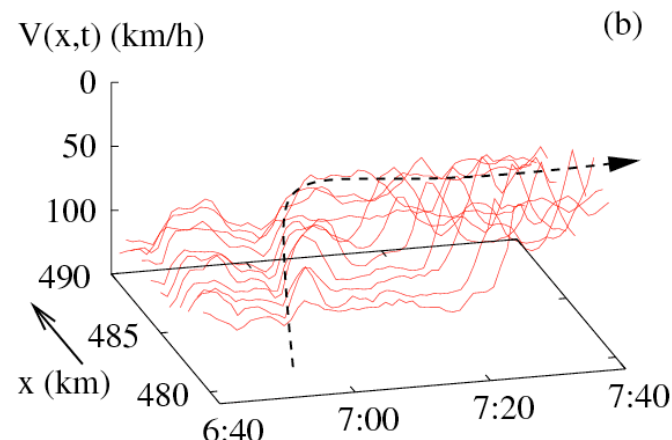


# Transitions from Free Traffic to Jams Do Exist

A5 South, 09/25/2001 (Tue.)

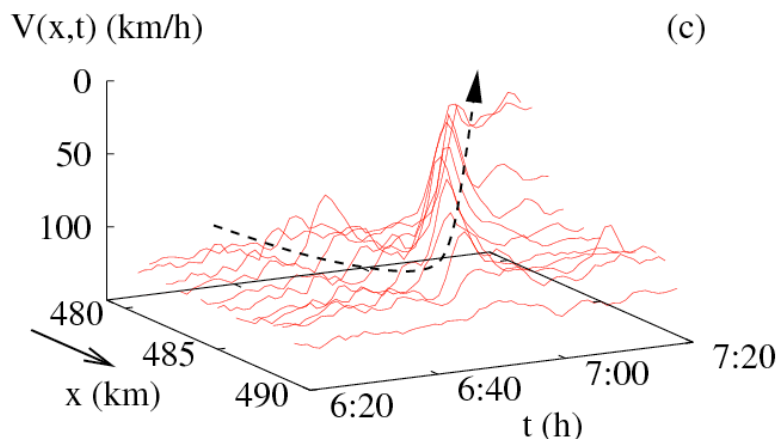


A5 South, 09/25/2001 (Tue.)

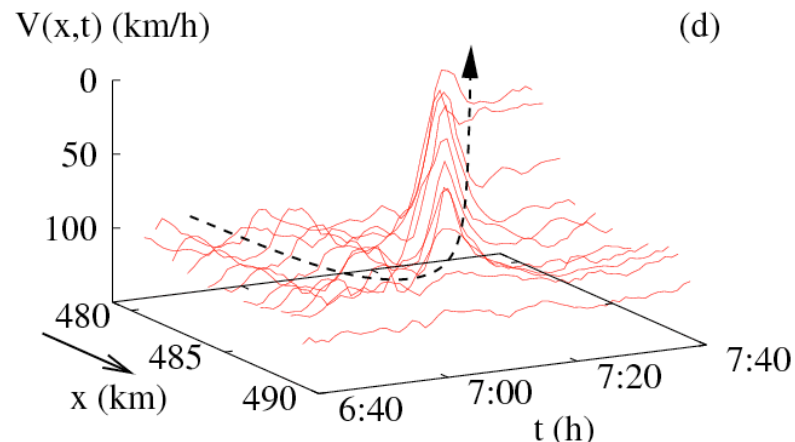


The underlying dynamics of this transition is a “boomerang effect”

A5 South, 05/10/2001 (Thu.)

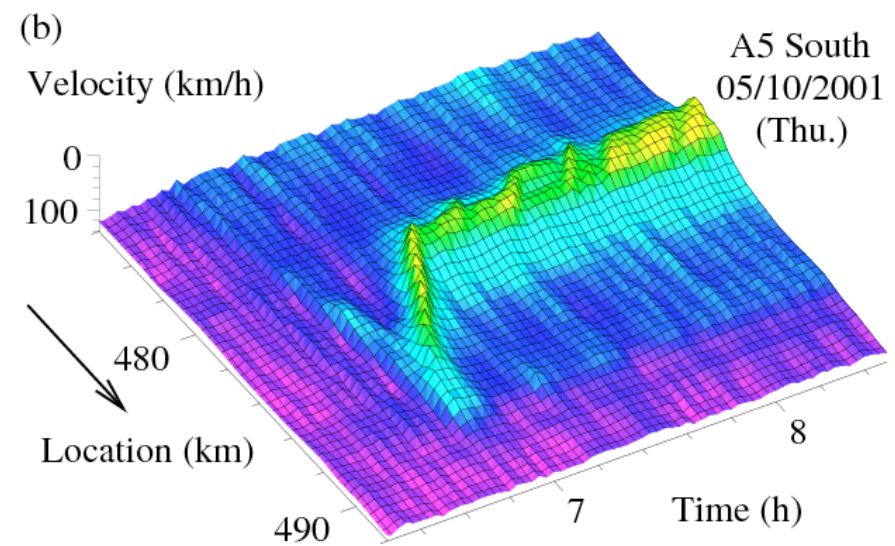
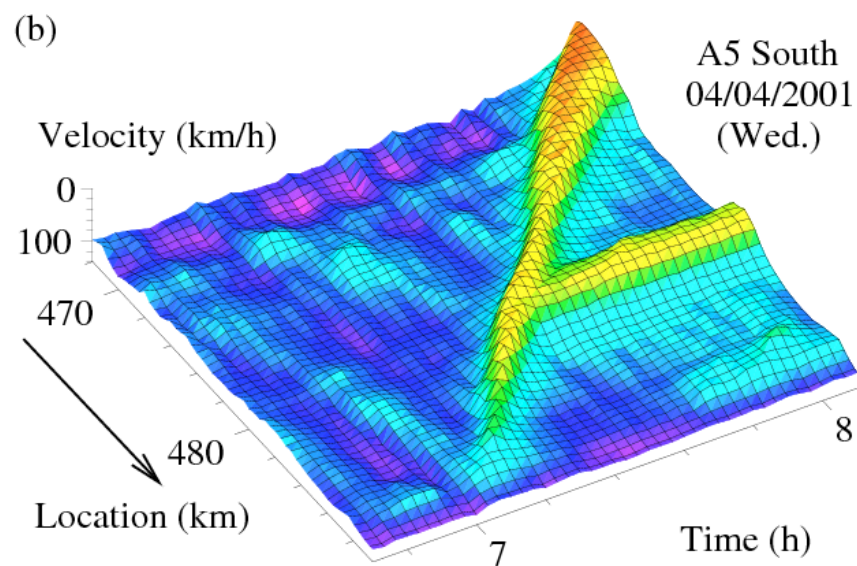


A5 South, 04/04/2001 (Wed.)



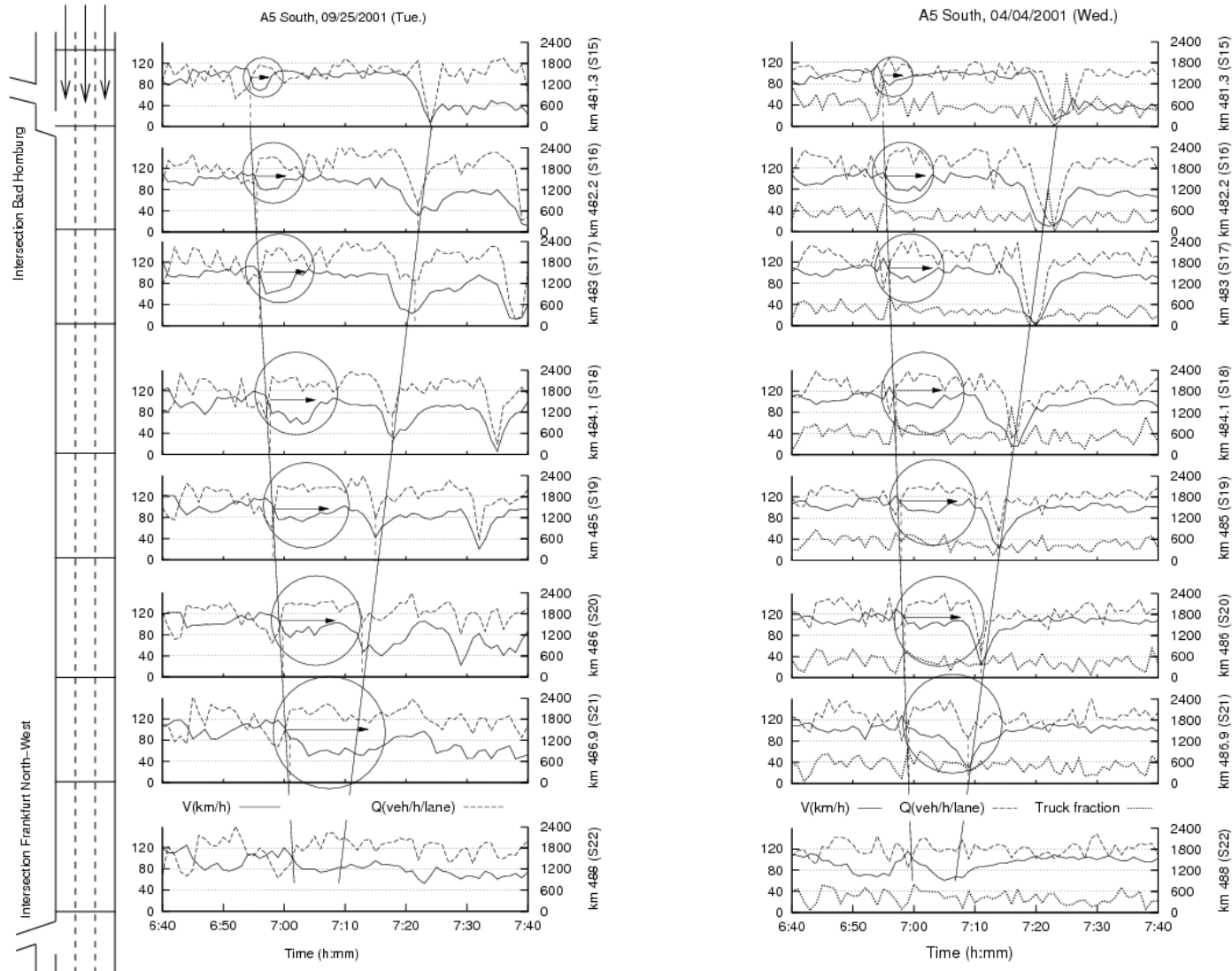
The boomerang effect was observed in 18 out of 245 cases of traffic breakdowns.

## Examples of the “Boomerang Effect”

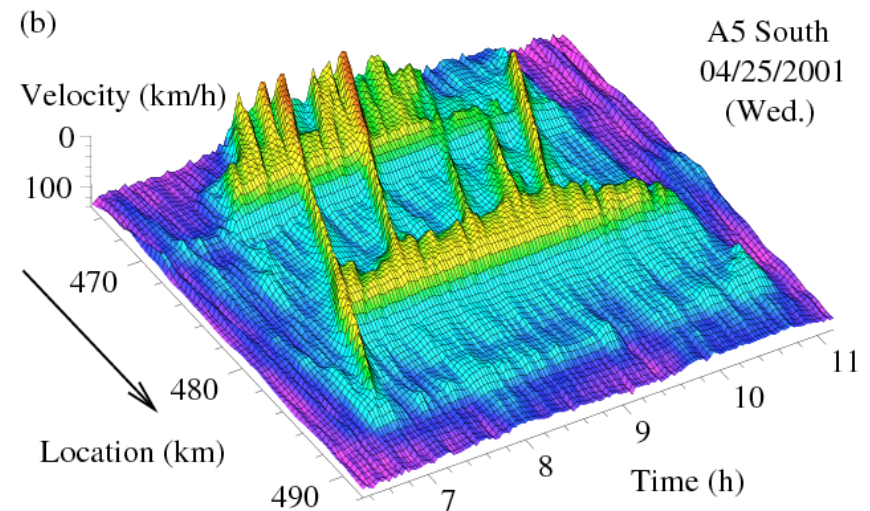
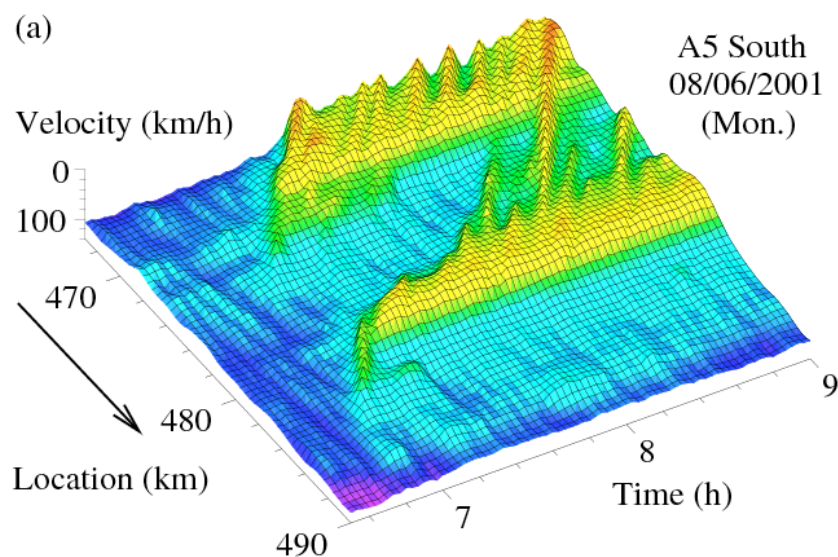




# Boomerang Effects are Due to Overtaking Trucks

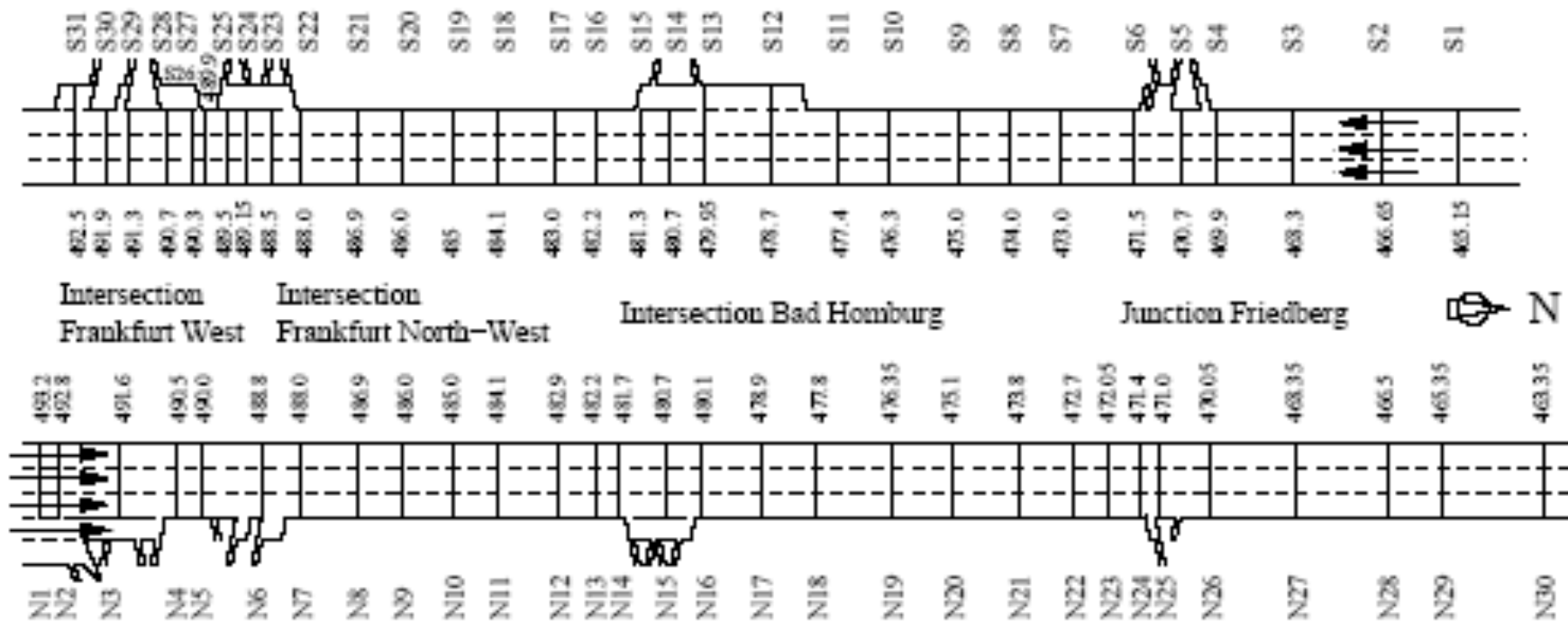


## Discussion of the General Pattern and Pinch Effect



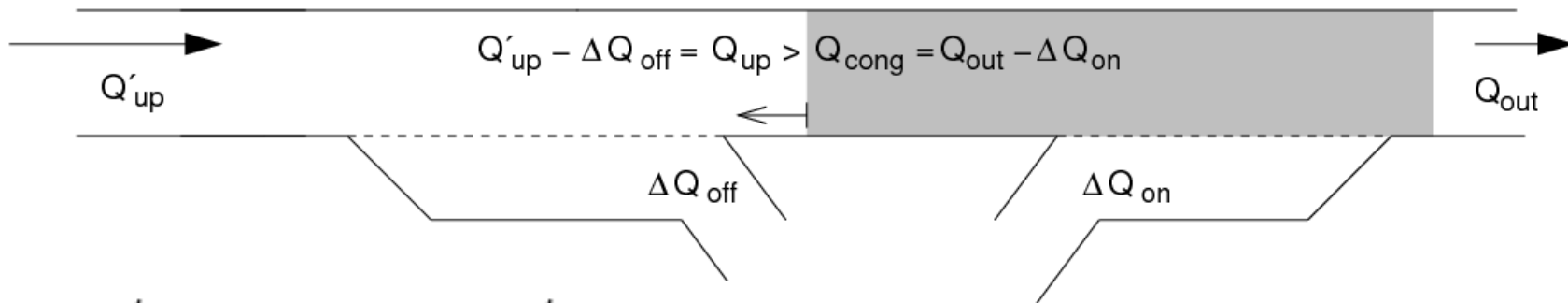
According to Kerner, in the “**generalized pattern**”, synchronized traffic upstream of a bottleneck breads wide moving jams based on the “**pinch effect**”. That is, upstream of a section with “synchronized” congested traffic close to a bottleneck, a so-called “pinch region” gives spontaneously birth to narrow vehicle clusters. These perturbations should be growing while traveling further upstream. Eventually, wide moving jams form by the merging or disappearance of narrow jams. Once formed, wide jams suppress the occurrence of new narrow jams in between.

# Design of the German Freeway A5

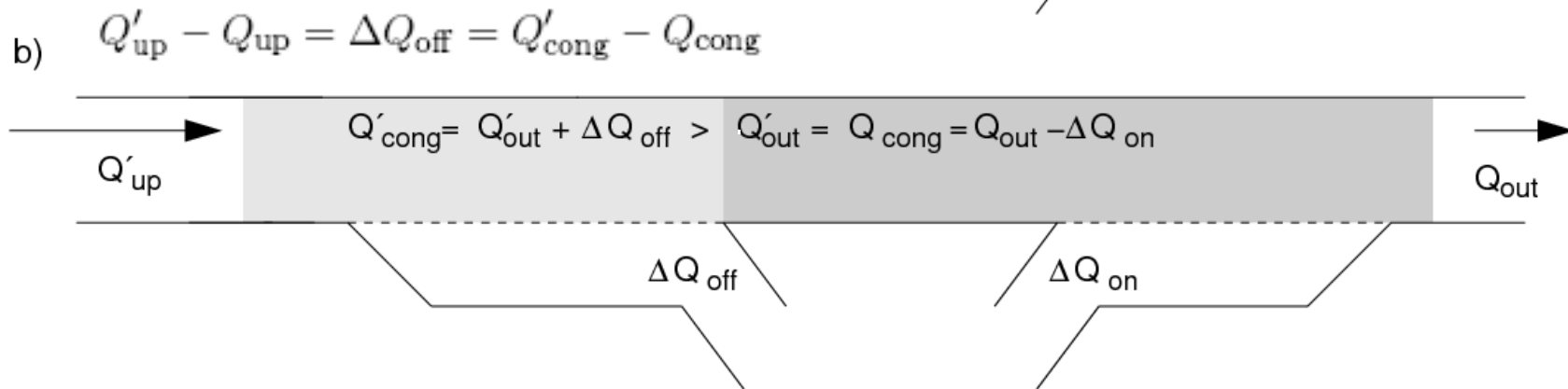


## (Intermittent) Activation of an Off-Ramp Bottleneck

a)



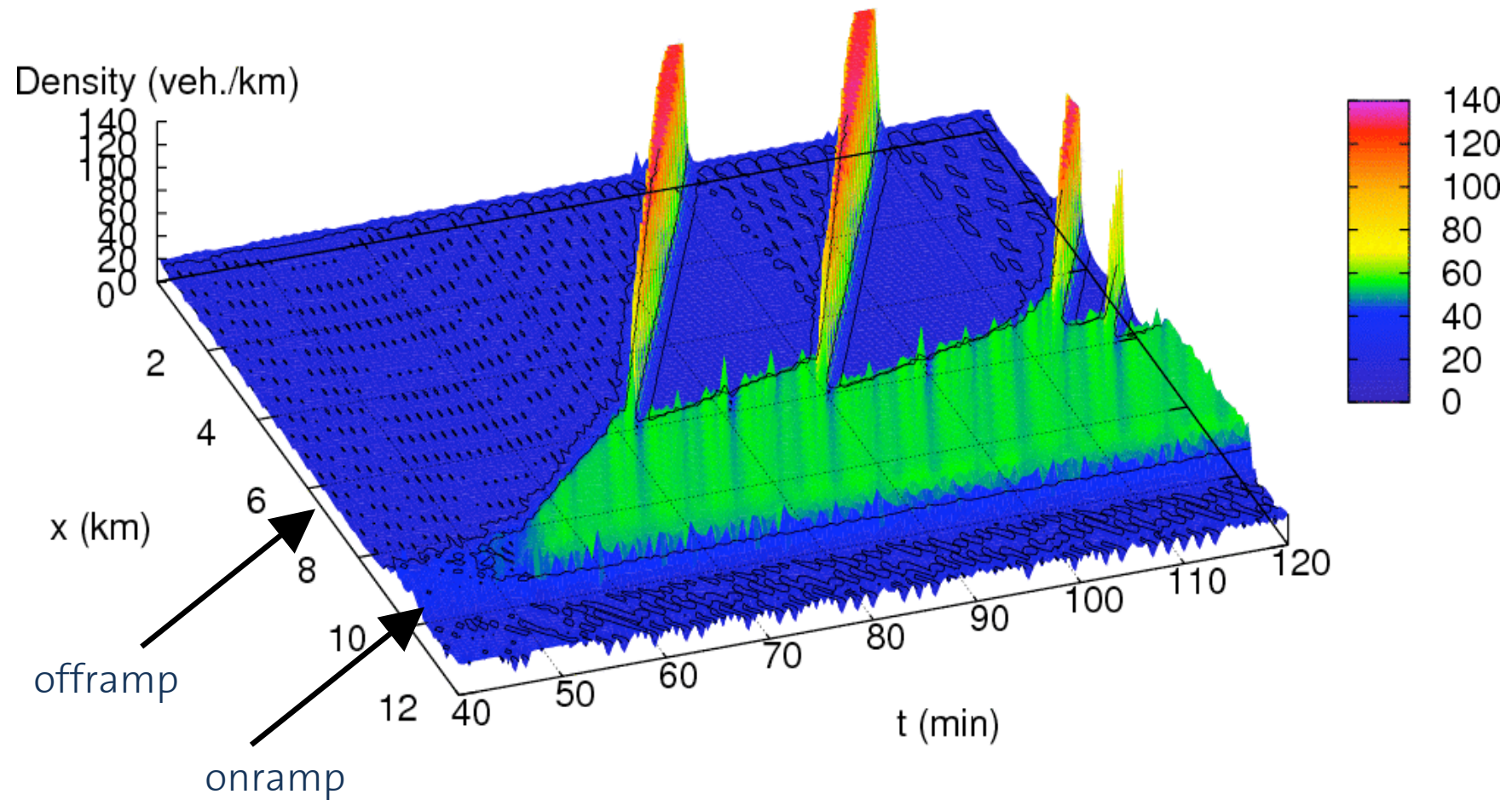
b)



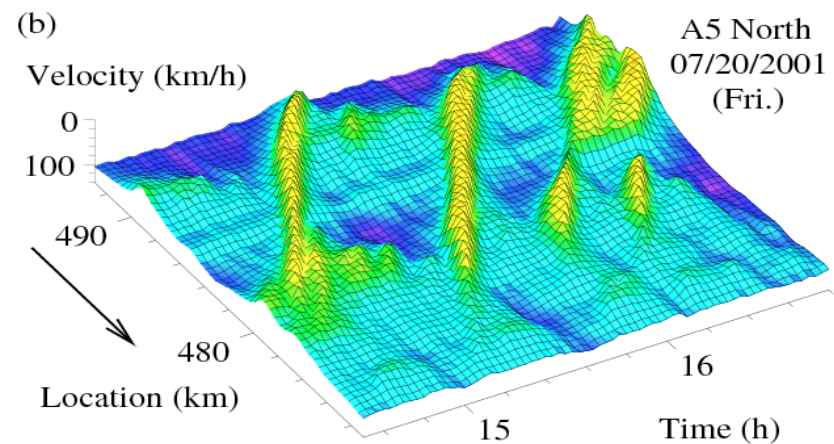
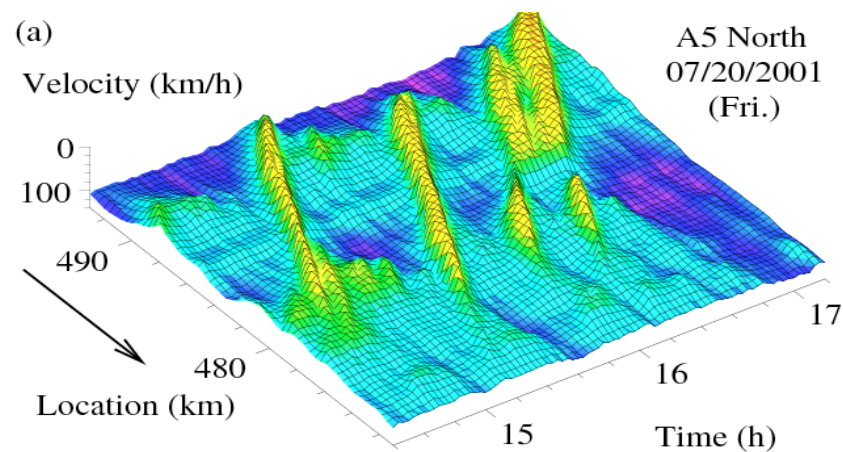
$$\Delta Q = \max(\Delta Q_{on} - \Delta Q_{off}, 0) = \max\left(\frac{Q_{rmp}}{n} - \frac{Q'_{rmp}}{n'}, 0\right) \leq \Delta Q_{on}$$

Milder form of congested traffic upstream of off-ramp expected, e.g. OCT or SGW instead of HCT. Appearance would correspond to “generalized pattern”.

## Combination of an Off-Ramp with an On-Ramp



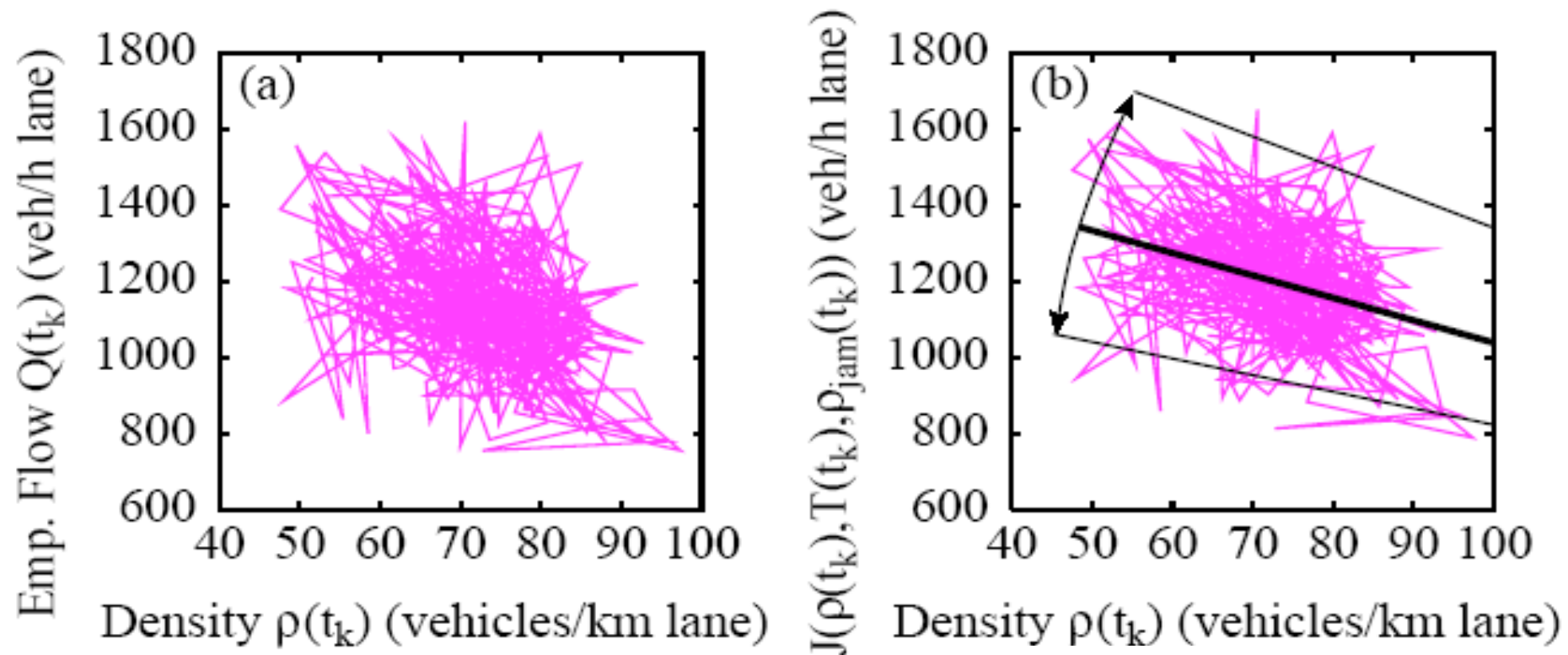
# Stop-and-Go Waves Emerging at a Gradient Look Different



# Instability of Traffic Flow



## Wide Scattering as Effect of Heterogeneous Traffic

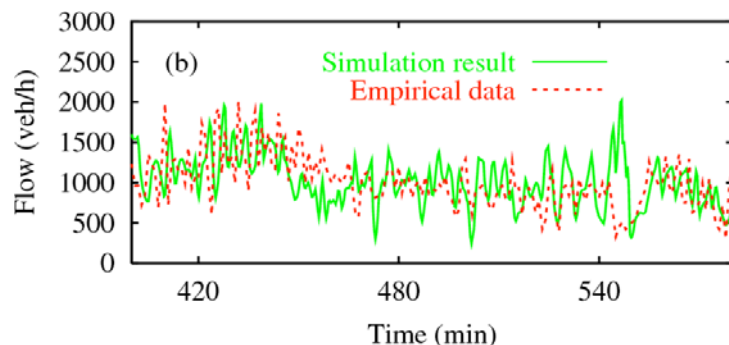
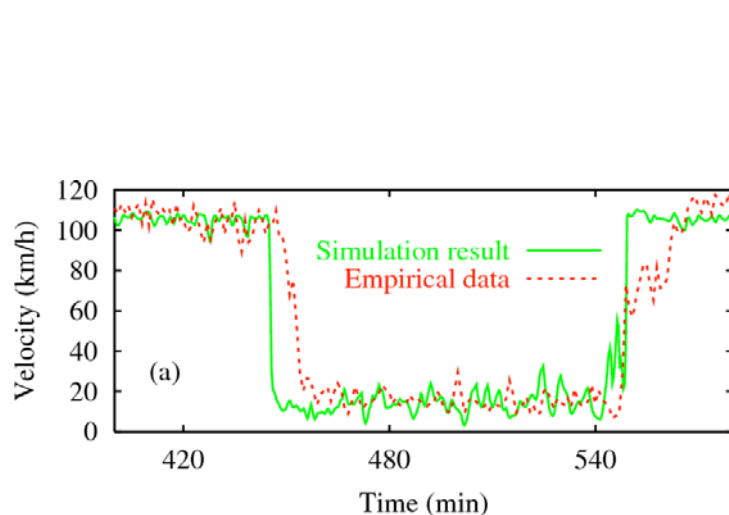


$$Q(t) = \frac{1}{T(t)} \left( 1 - \frac{\rho(t)}{\rho_{jam}(t)} \right)$$

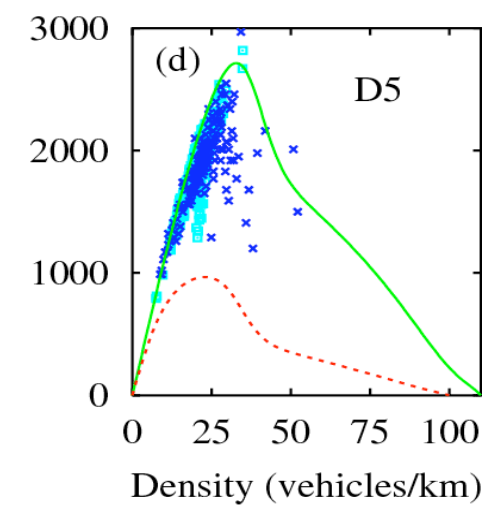
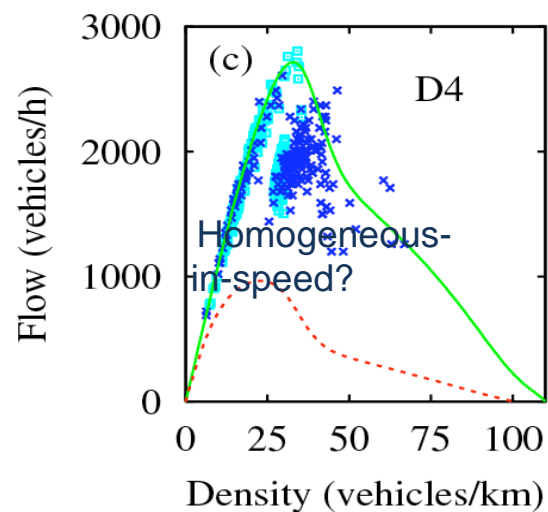
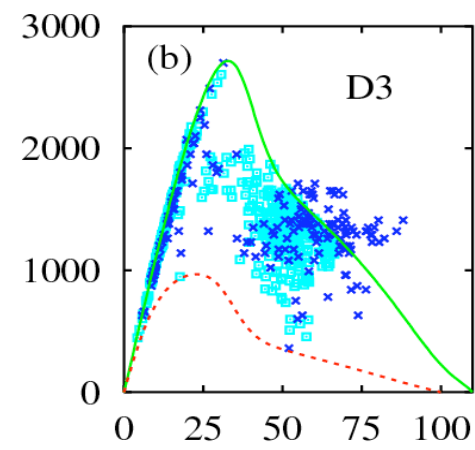
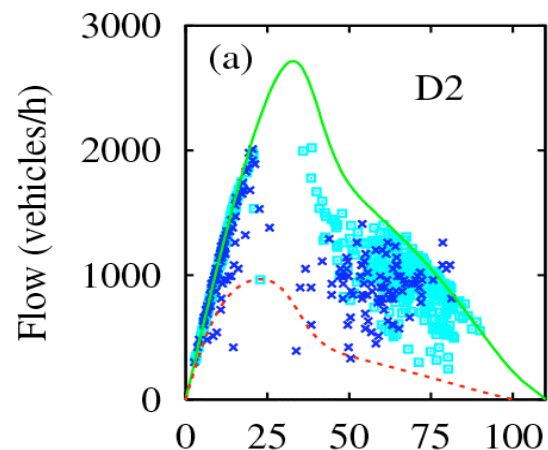
The jam line with variable parameters can explain the observations quantitatively!  
Scattering and stochasticity do not contradict models with a fundamental diagram,  
just models with identical driver-vehicle units.



# Fluid-Dynamic Traffic Simulation of Multi-Class Traffic



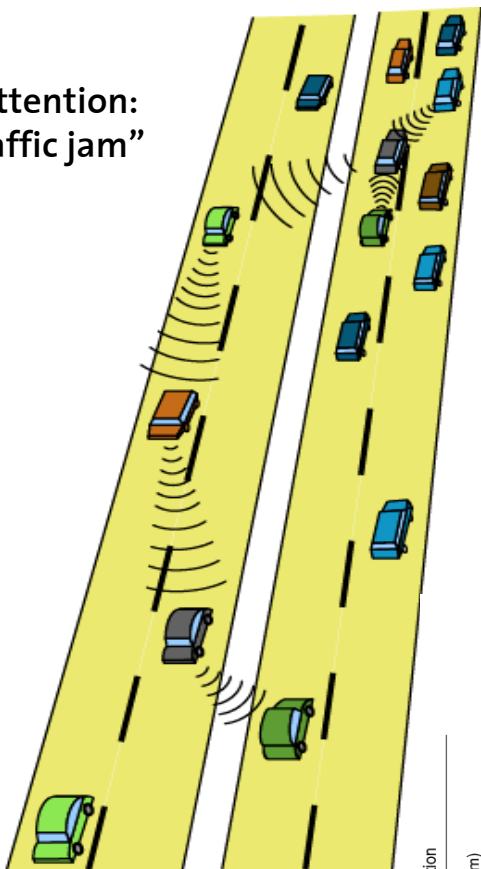
► Time series



► Fundamental diagram

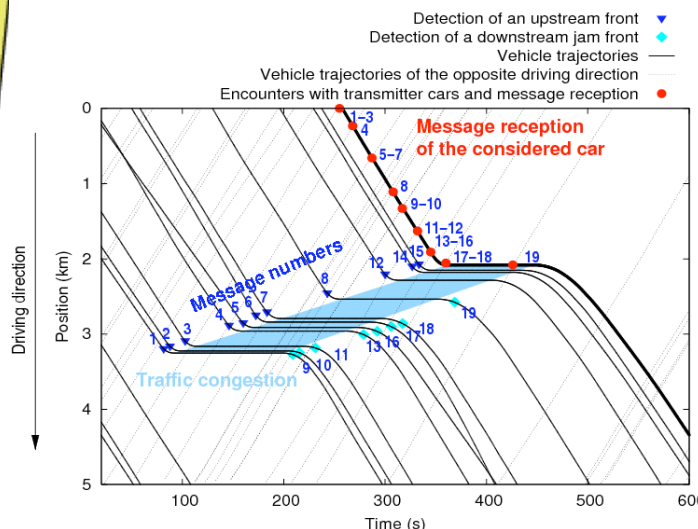
# Cooperative Driving Based on Autonomous Vehicle Interactions

“Attention:  
Traffic jam”

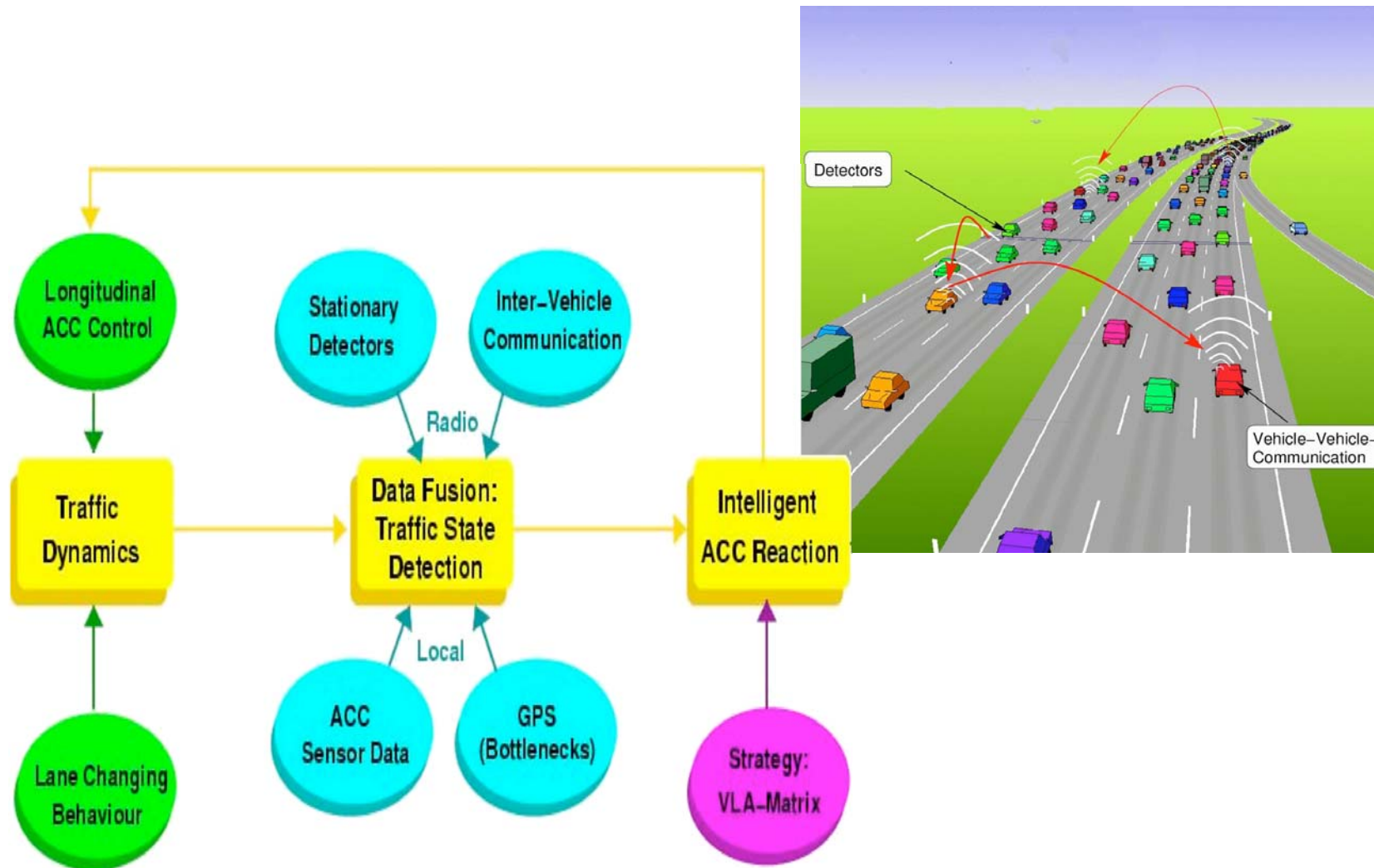


In: *Transportation Research Record* (2007)

- On-board data acquisition („perception“)
- Inter-vehicle communication
- Cooperative traffic state determination (“cognition“)
- Adaptive choice of driving strategy (“decision-making“)
- Driver information
- Traffic assistance (higher stability and capacity of traffic flow)

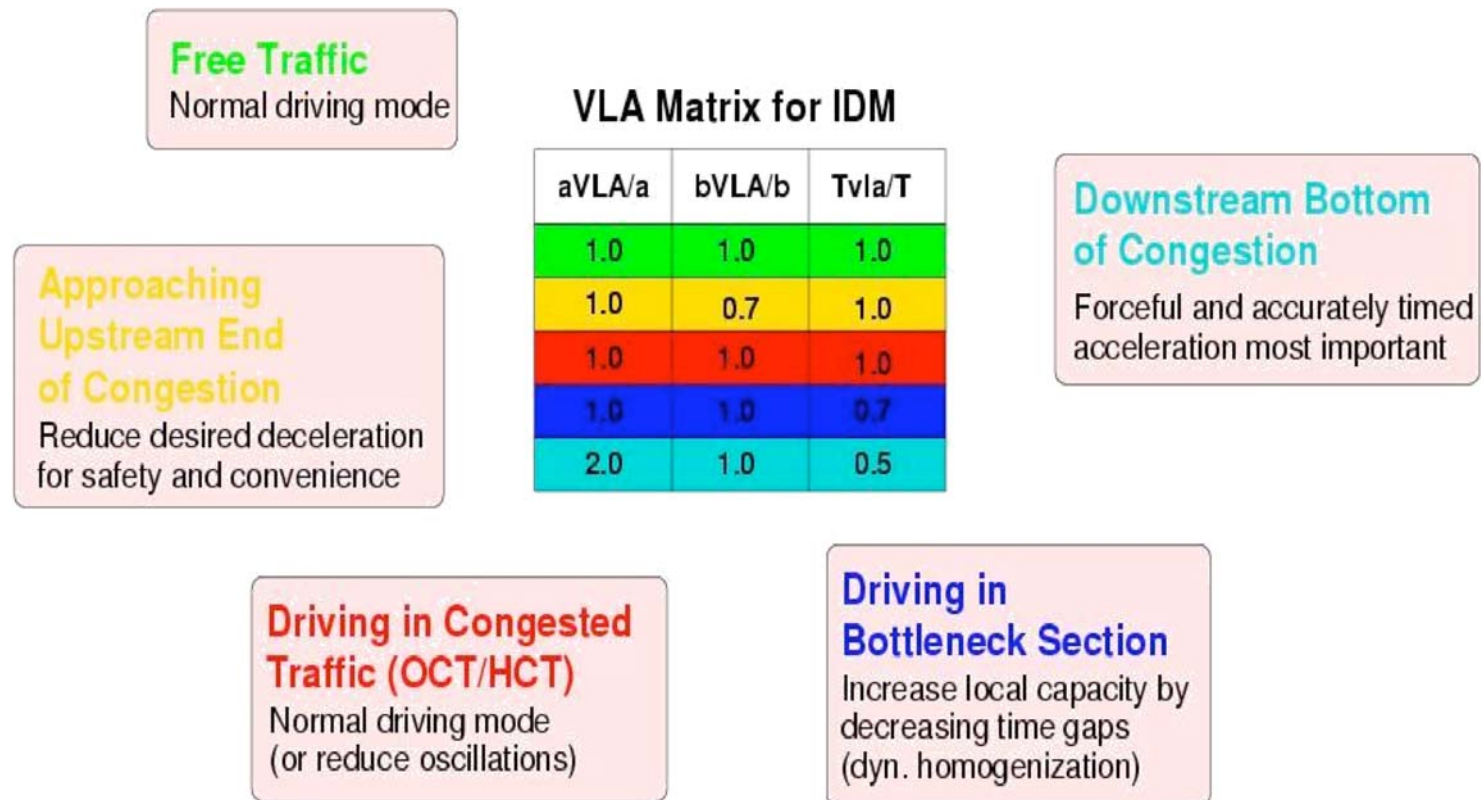


# Data Fusion for Dynamic Traffic State Detection



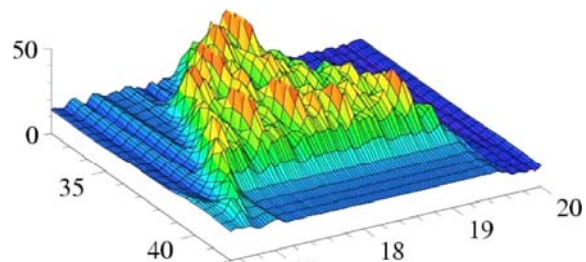
# Design of Traffic State Adaptive Cruise Control

Invent-VLA: Intelligent Adaptive Cruise Control (IACC) for the avoidance of traffic breakdowns and a faster recovery from congested traffic

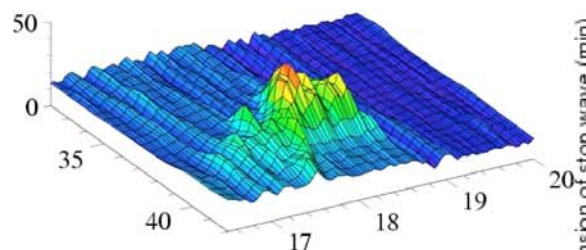


# Enhancing Traffic Performance by Adaptive Cruise Control

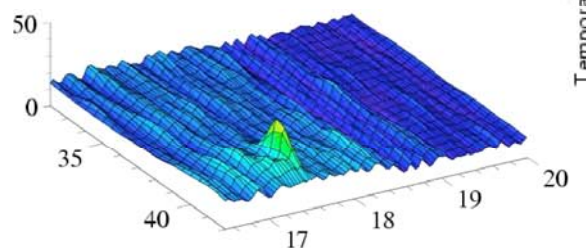
$\rho$ (veh./km/lane)



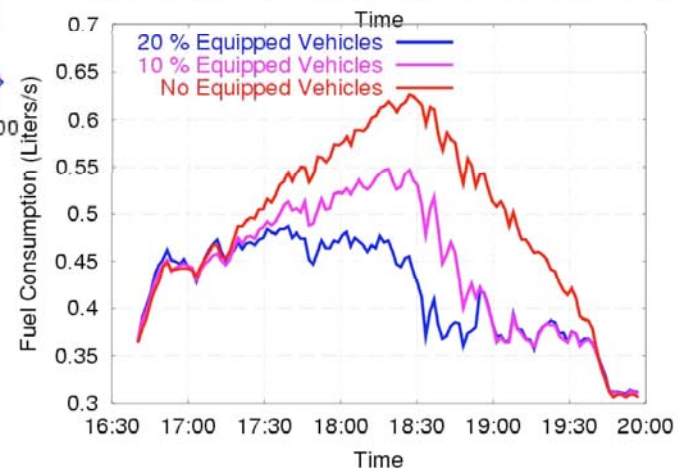
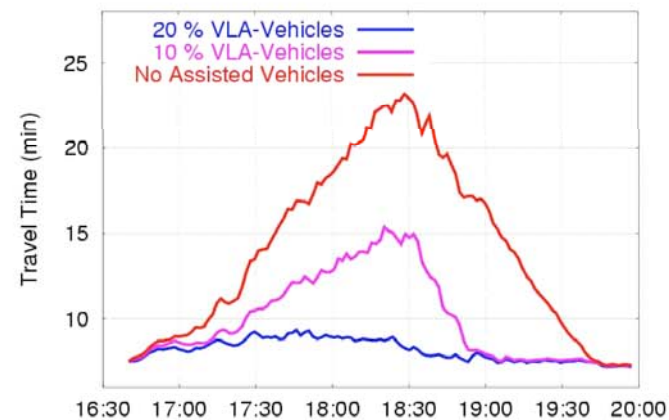
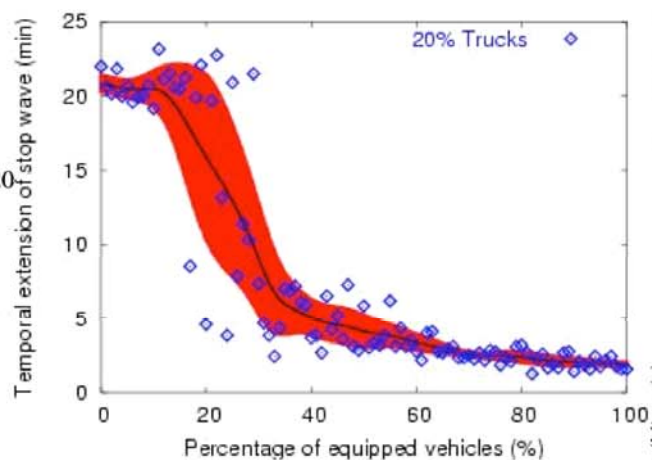
10% Equipped Vehicles



20% Equipped Vehicles



- Traffic breakdowns delayed
- Faster recovery to free traffic
- High impact on travel times
- Reduced fuel consumption and emissions



“Mechanism design”,  
in cooperation with



## 3D Assessment of Traffic Scenarios

